

A tutorial on Bayesian Optimization

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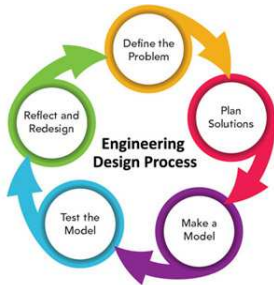
Challenges in Engineering Design

The society demands new products of better quality, functionality, usability, etc.!



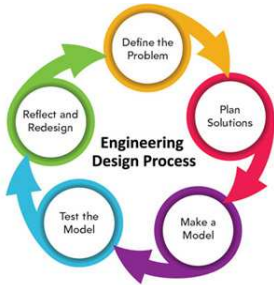
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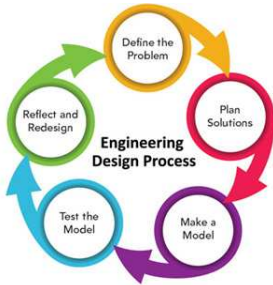
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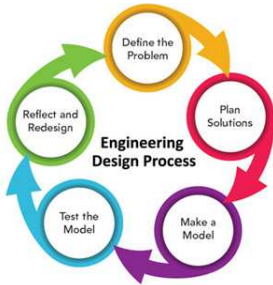
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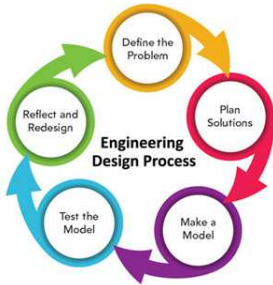
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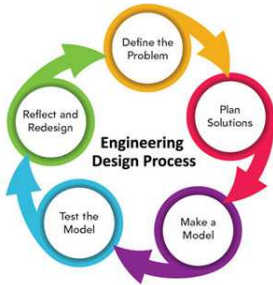
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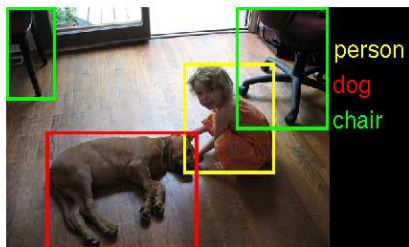
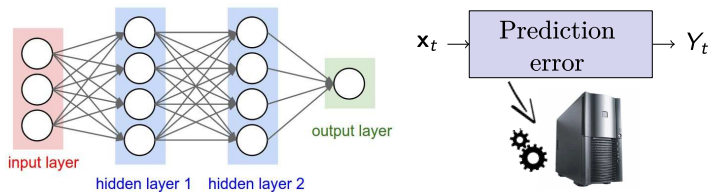
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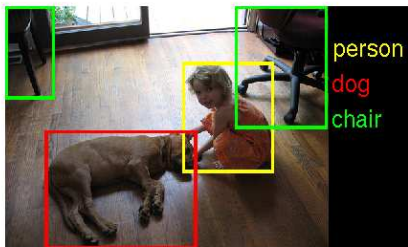
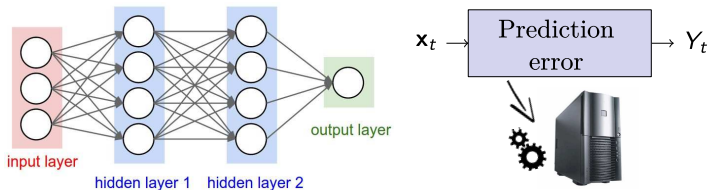
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Optimization is a challenging task in new products design!

Example: **Deep Neural Network** for object recognition.



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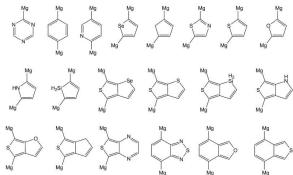
Parameters to tune: Number of neurons, number of layers, learning-rate, level of regularization, momentum, etc.

Example: new **plastic solar cells** for transforming light into electricity.



Library generation

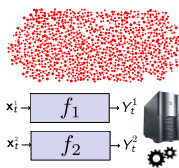
Fragments



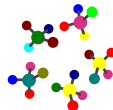
Bonding rules



Performance evaluation



Interesting molecules

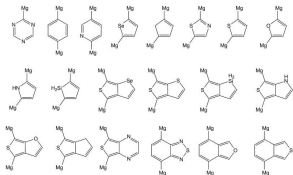


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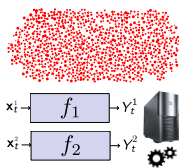
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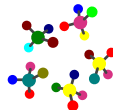
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Performance evaluation



Interesting molecules



Explore **millions of candidate molecule structures** to identify the compounds with the best properties.

Example: **control system** for a robot that is able to grasp objects.



Finger Joint Trajectories



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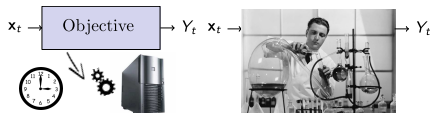
Finger Joint Trajectories



Parameters to tune: initial pose for the robot's hand and finger joint trajectories.

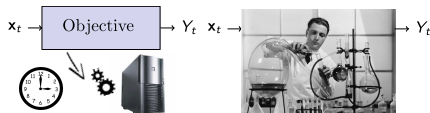
Optimization Problems: Common Features

- Very expensive evaluations.

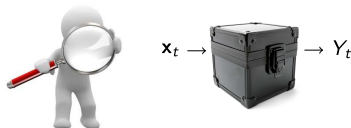


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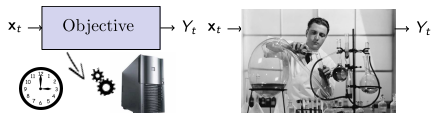


- The objective is a black-box.

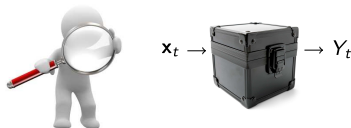


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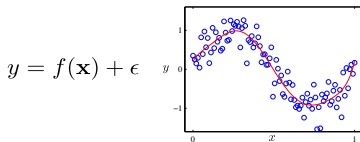
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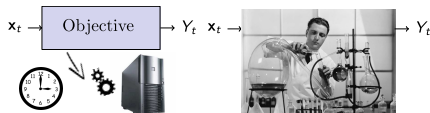


- The evaluation can be noisy.

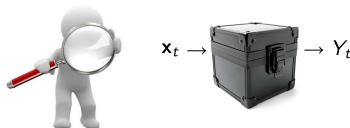


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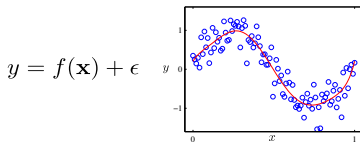
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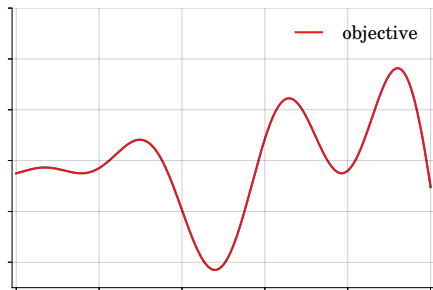


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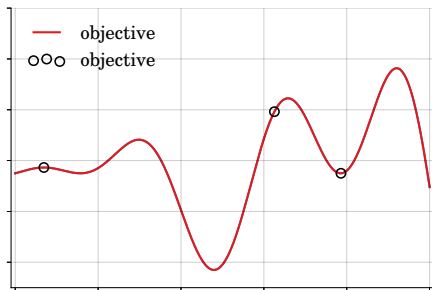
Bayesian optimization methods can be used to solve these problems!

Bayesian Optimization in Practice



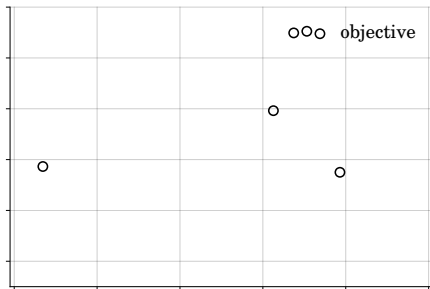
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Bayesian Optimization in Practice



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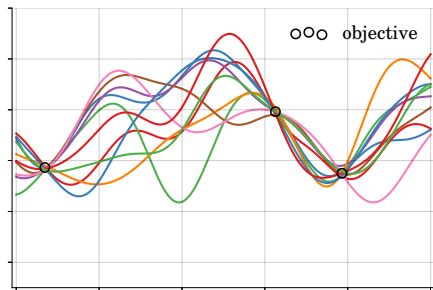


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② Fit a model to the data:

$$p(y|\mathbf{x}, \mathcal{D}_n).$$

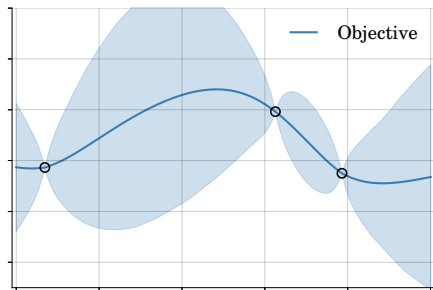
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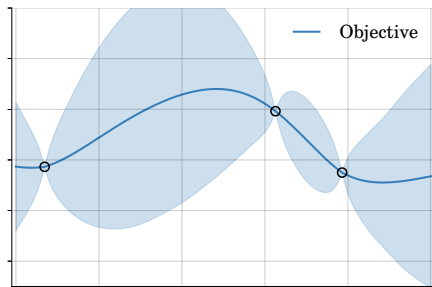
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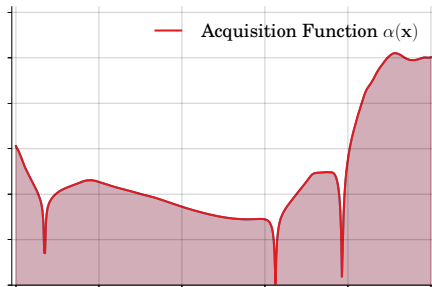
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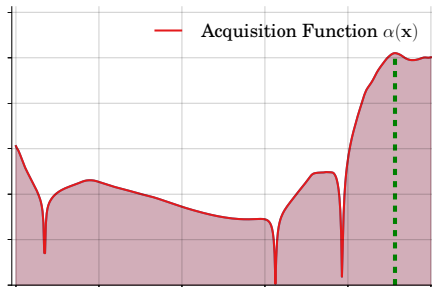
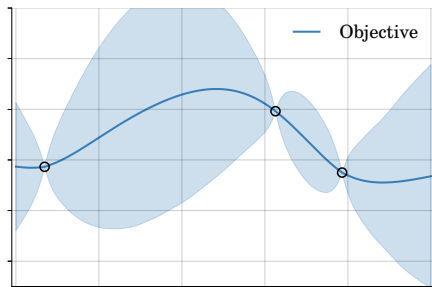
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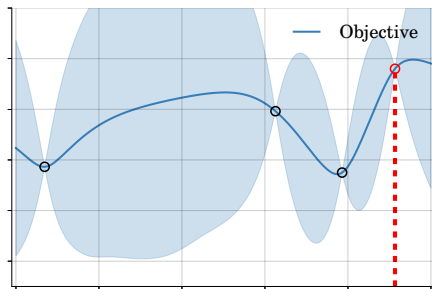
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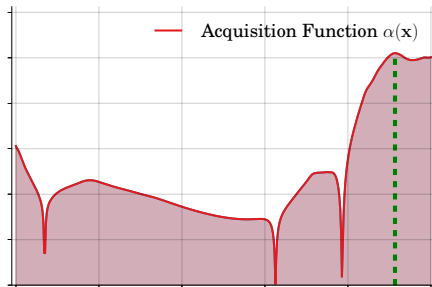
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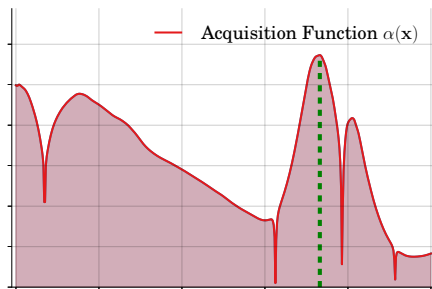
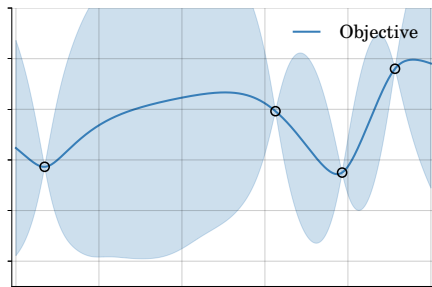
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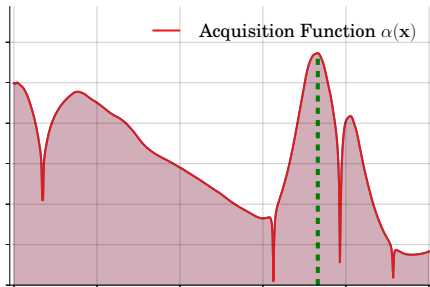
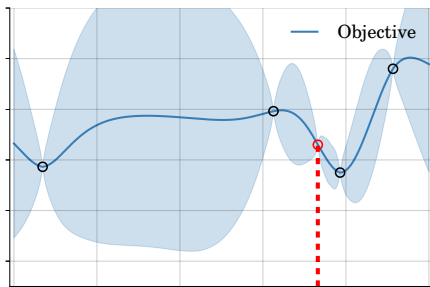
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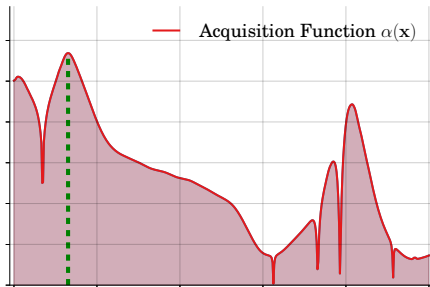
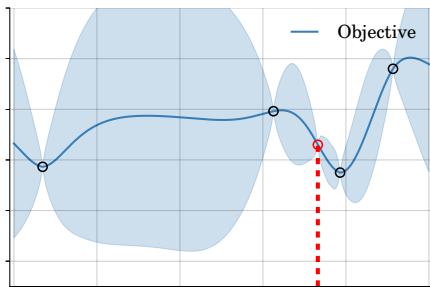
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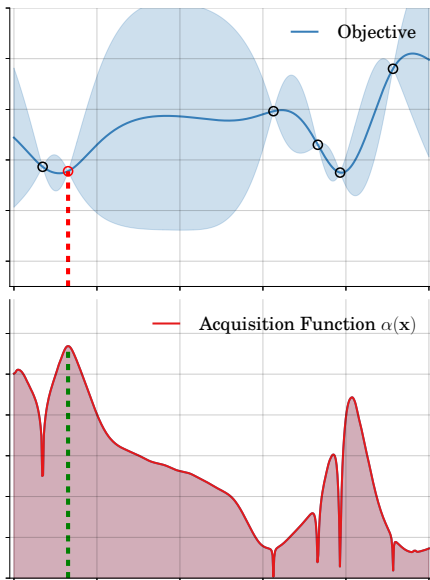
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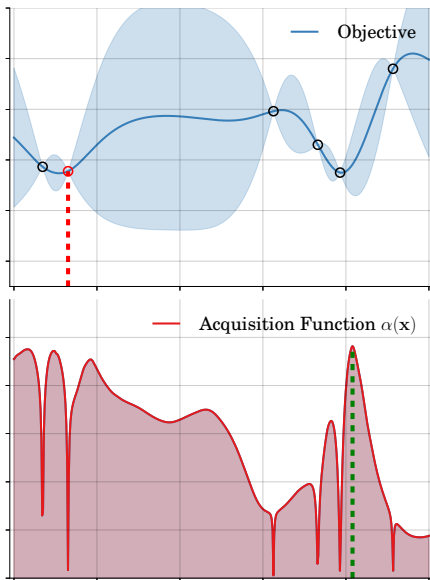
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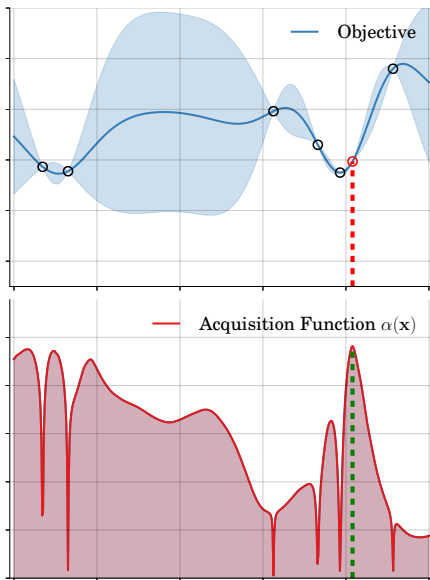
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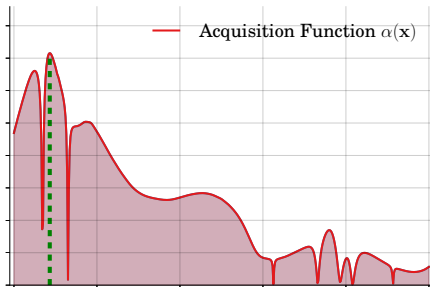
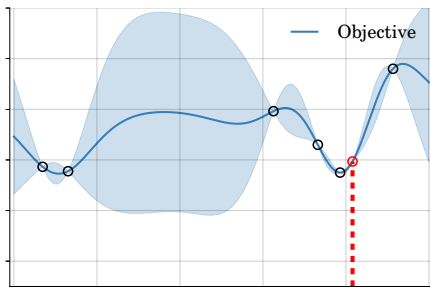
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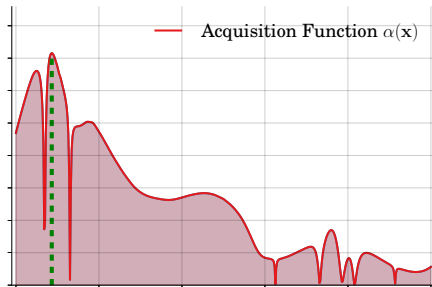
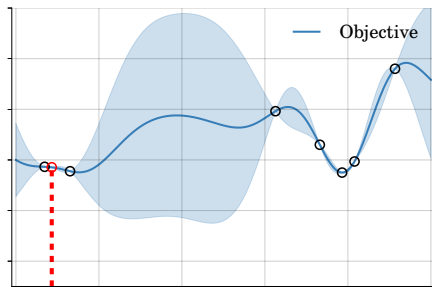
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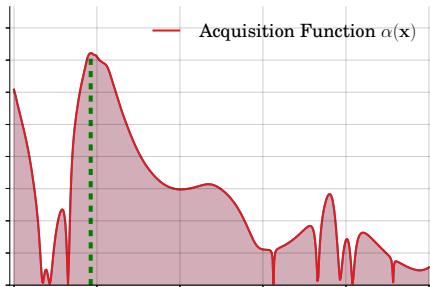
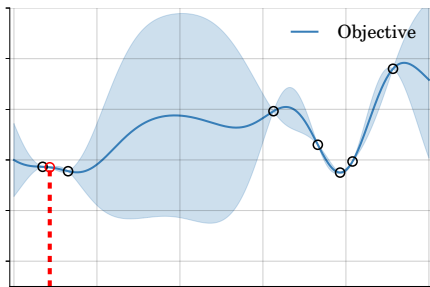
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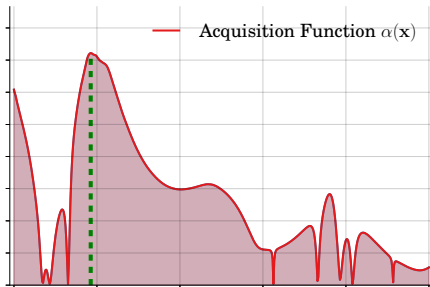
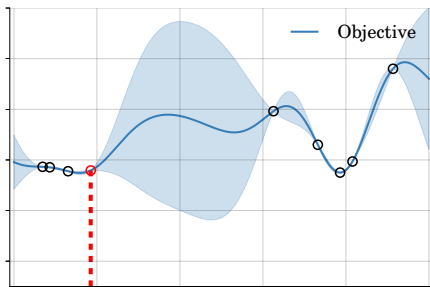
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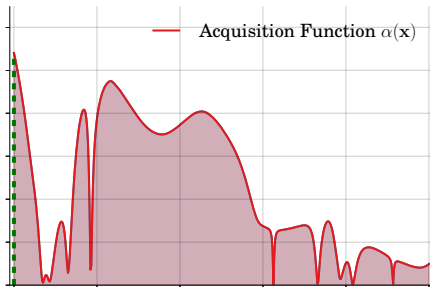
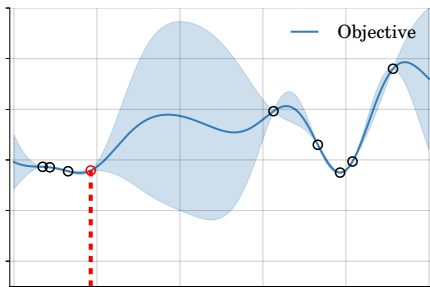
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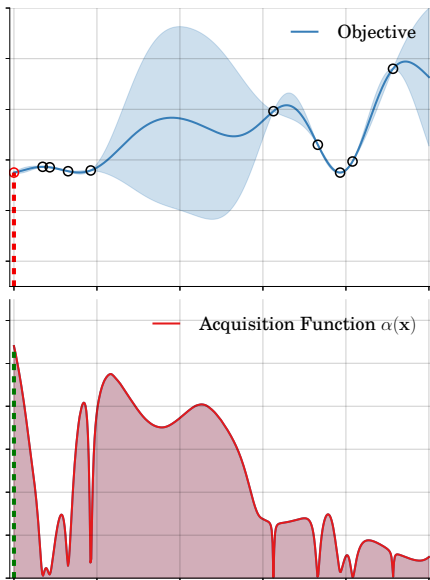
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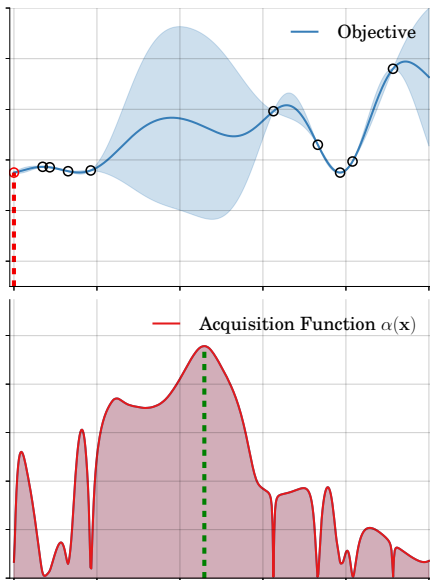
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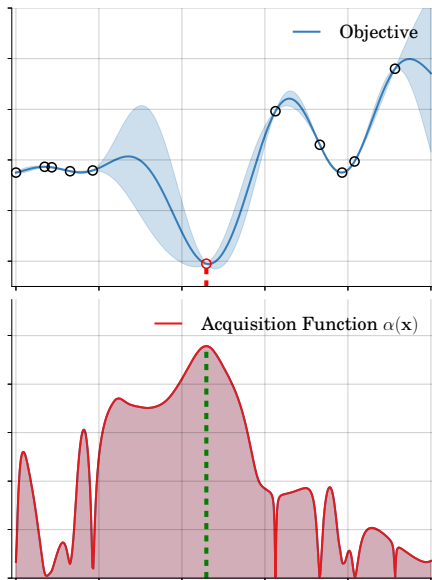
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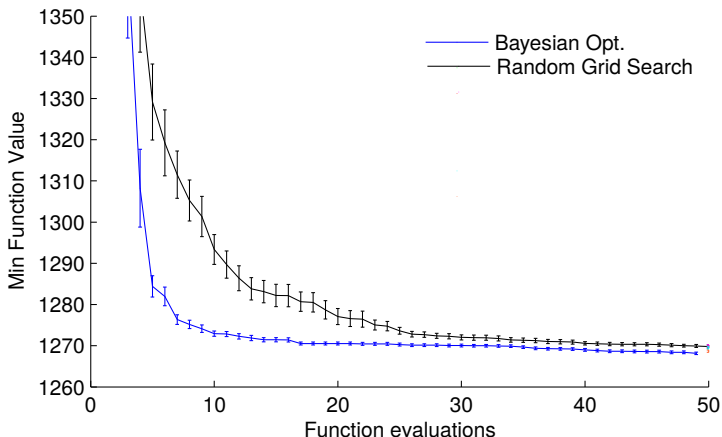
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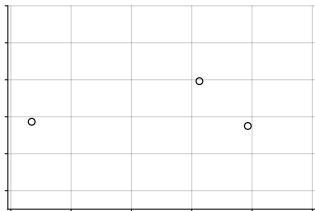
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Bayesian Optimization vs. Uniform Exploration

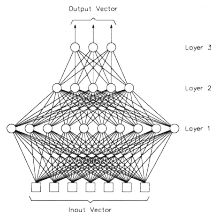
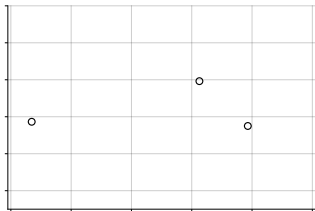


Tuning LDA on a collection of Wikipedia articles (Snoek *et al.*, 2012).

Fitting a Model to the Data



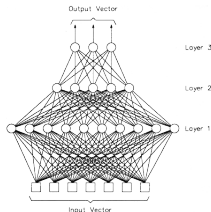
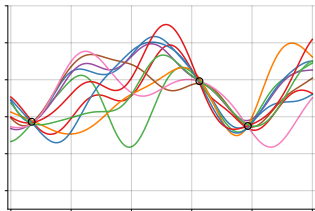
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$$h_j(\mathbf{x}) = \tanh\left(\sum_{i=1}^I x_i w_{ji}\right)$$

$$f(\mathbf{x}) = \sum_{j=1}^H v_j h_j(\mathbf{x})$$

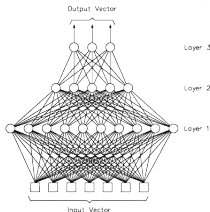
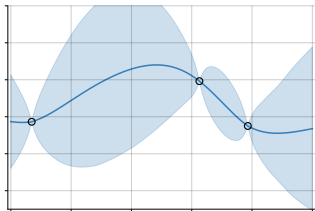
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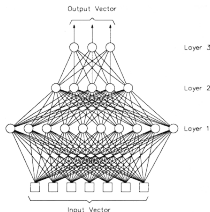
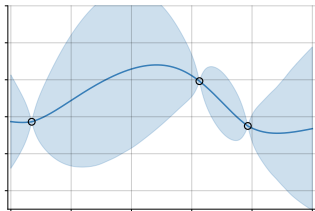
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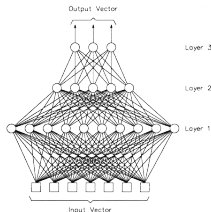
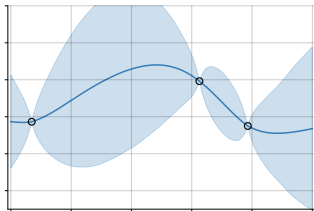
Posterior Dist.

$$p(\mathbf{W}|\text{Data}) = p(\mathbf{W})p(\text{Data}|\mathbf{W})/p(\text{Data})$$

Predictive Dist.

$$p(y|\text{Data}, x) = \int p(y|\mathbf{W}, x) p(\mathbf{W}|\text{Data}) d\mathbf{W}$$

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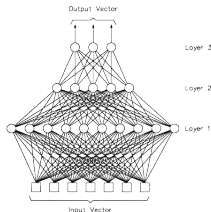
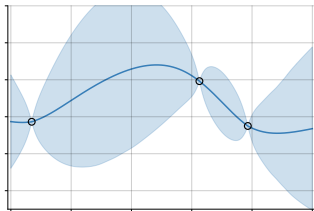
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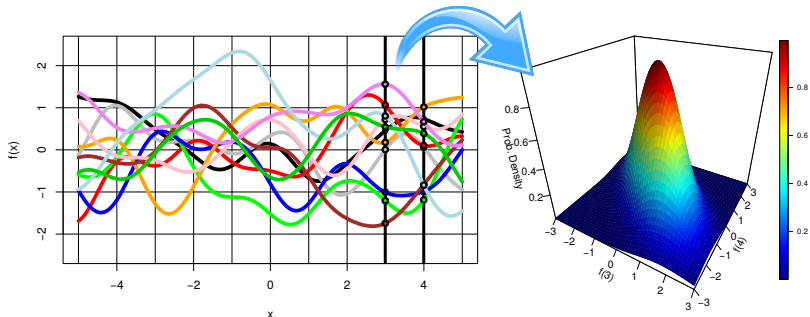
Solved by setting $p(\mathbf{W}) = \prod_{ij} \mathcal{N}(w_{ji}|0, \sigma^2 H^{-1})$ and letting $H \rightarrow \infty$!

Gaussian Processes

Distribution over functions $f(\cdot)$ so that for any finite $\{\mathbf{x}_i\}_{i=1}^N$, $(f(\mathbf{x}_1), \dots, f(\mathbf{x}_N))^T$ follows an N -dimensional Gaussian distribution.

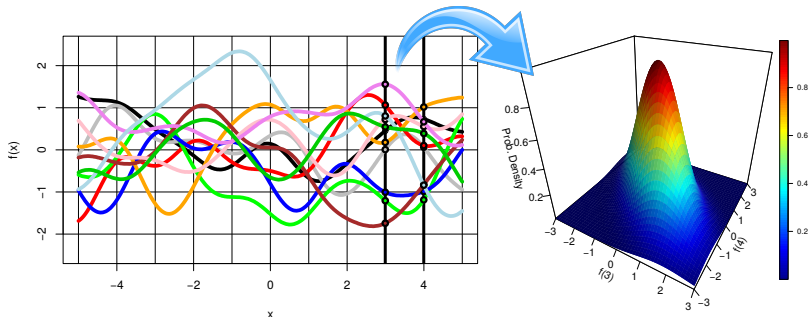
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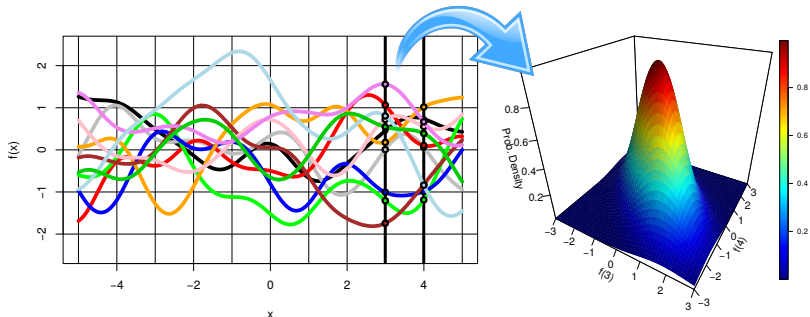
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Due to Gaussian form, there are closed-form solutions for many useful questions about finite data.

Gaussian Processes

- The **joint distribution** for \mathbf{y}^* at test points $\{\mathbf{x}_m^*\}_{m=1}^M$ and \mathbf{y} :

$$p(\mathbf{y}^*, \mathbf{y}) = \mathcal{N} \left(\begin{bmatrix} \mathbf{0} \\ \mathbf{0} \end{bmatrix}, \begin{bmatrix} \mathbf{k}_\theta & \mathbf{K}_\theta \\ \boldsymbol{\kappa}_\theta & \mathbf{k}_\theta^\top \end{bmatrix} \right)$$

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- These **matrices** are computed from the covariance $C(\cdot, \cdot; \theta)$:

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- The **predictive distribution** for \mathbf{y}^* given \mathbf{y} , $p(\mathbf{y}^*|\mathbf{y})$, is:

$$\begin{aligned} \mathbf{y}^* &\sim \mathcal{N}(\mathbf{m}, \Sigma) \\ \mathbf{m} &= \mathbf{k}_\theta^\top \mathbf{K}_\theta^{-1} \mathbf{y}, \quad \Sigma = \boldsymbol{\kappa}_\theta - \mathbf{k}_\theta^\top \mathbf{K}_\theta^{-1} \mathbf{k}_\theta, \end{aligned}$$

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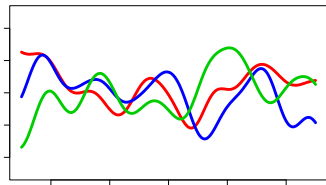
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- The log of the **marginal likelihood**, $p(\mathbf{y}|\theta)$, is:

$$\log p(\mathbf{y}) = -\frac{N}{2} \log 2\pi - \frac{1}{2} \log |\mathbf{K}_\theta| - \frac{1}{2} \mathbf{y}^\top \mathbf{K}_\theta^{-1} \mathbf{y}$$

Some Covariance Functions

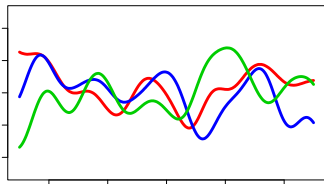
Squared Exponential



$$C(\mathbf{x}, \mathbf{x}') = \sigma^2 \exp \left\{ \frac{1}{2} \sum_j \left(\frac{x_j - x'_j}{l_j} \right)^2 \right\}$$

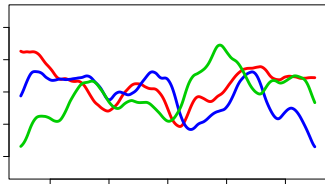
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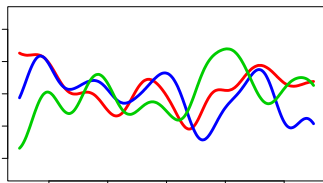
Matérn



$$C(\mathbf{x}, \mathbf{x}') = \frac{2^{1-\nu}}{\Gamma(\nu)} \left(\frac{\sqrt{2\nu}r}{l} \right)^\nu K_\nu \left(\frac{\sqrt{2\nu}r}{l} \right)$$

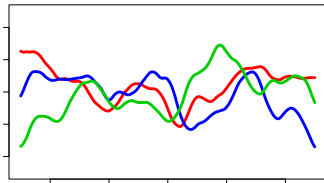
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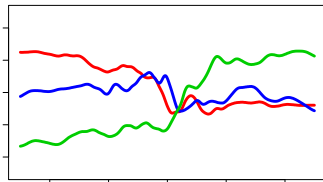
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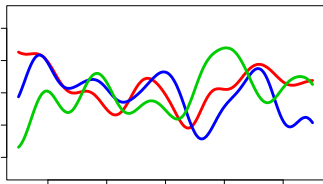
Neural Network



$$C(\mathbf{x}, \mathbf{x}') = \frac{2}{\pi} \sin^{-1} \left(\frac{2\mathbf{x}^T \mathbf{\Sigma} \mathbf{x}'}{\sqrt{(1+2\mathbf{x}^T \mathbf{\Sigma} \mathbf{x})(1+2\mathbf{x}'^T \mathbf{\Sigma} \mathbf{x}')}} \right)$$

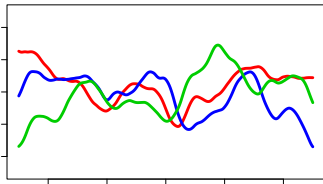
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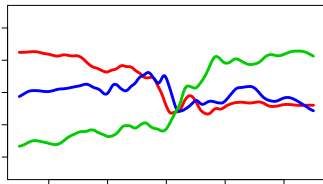
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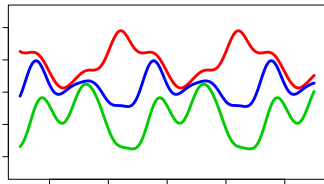
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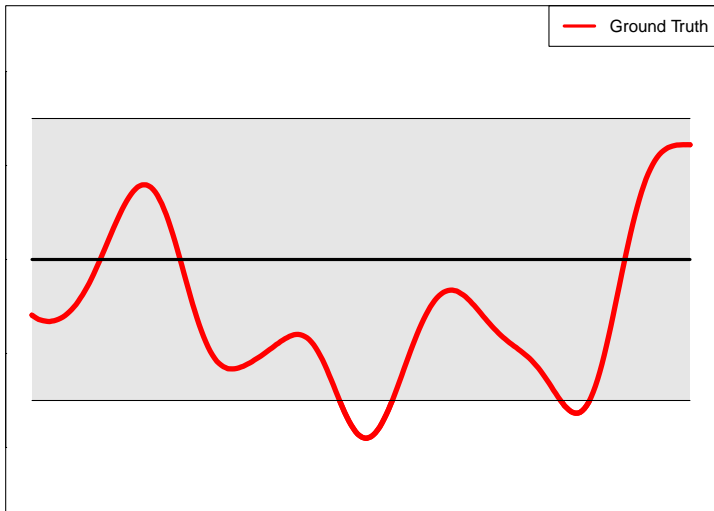
Periodic



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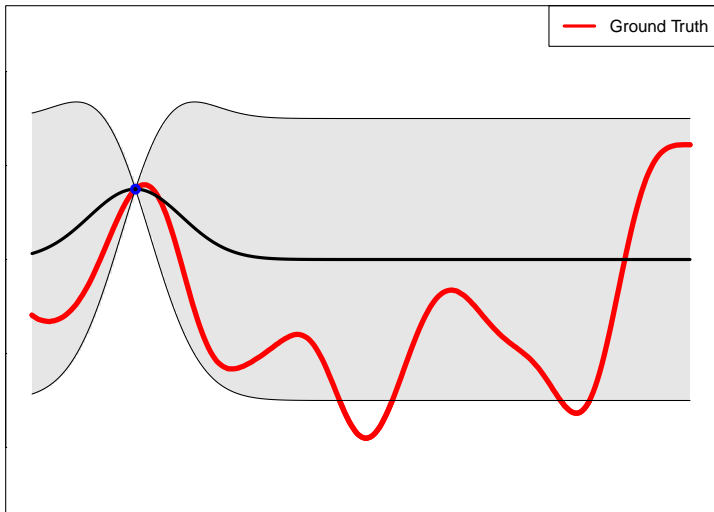
From the Prior to the Posterior

GP regression provides a **closed-form** posterior distribution for $f(\cdot)$.



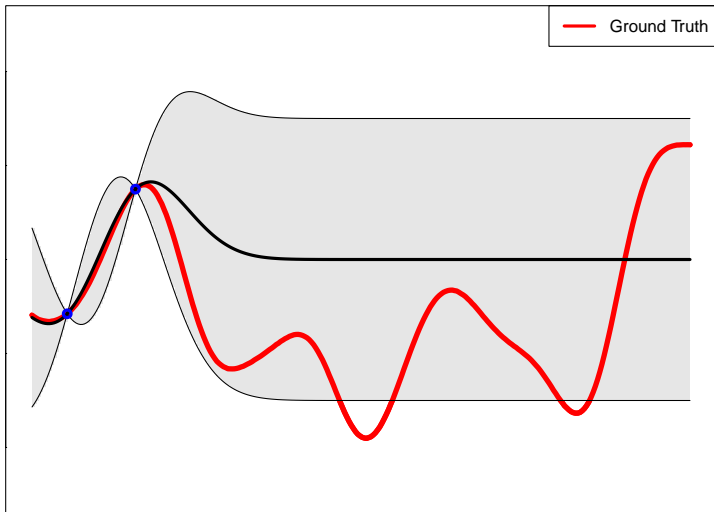
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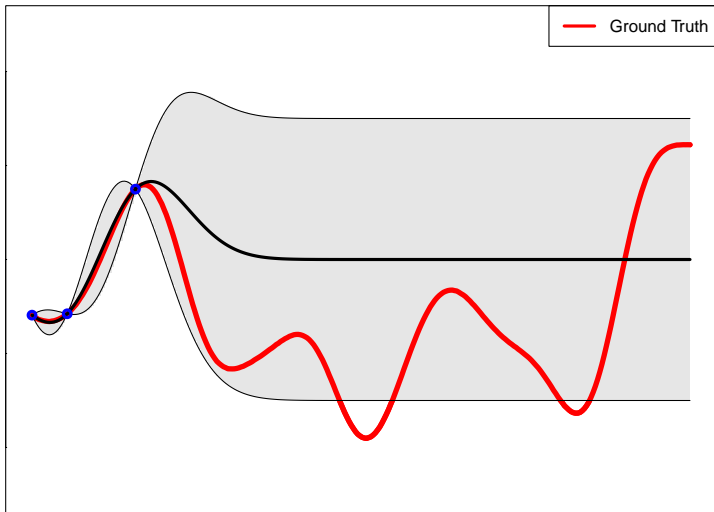
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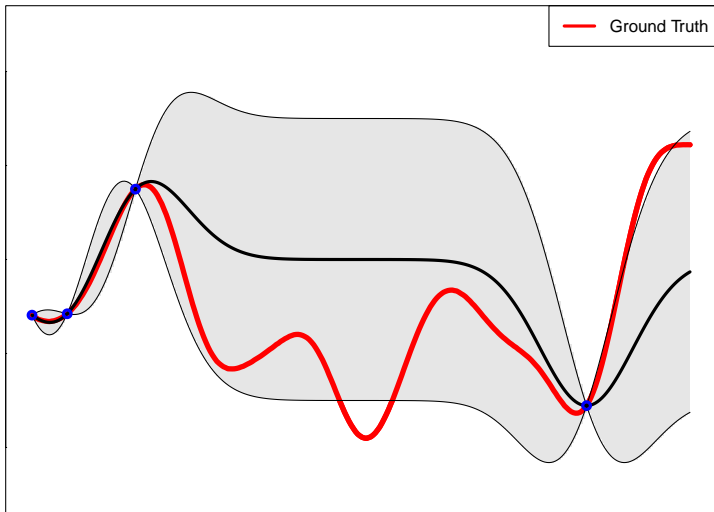
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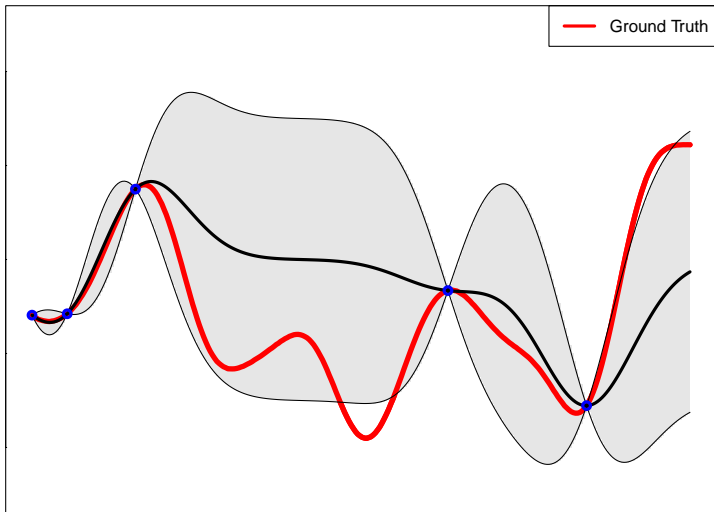
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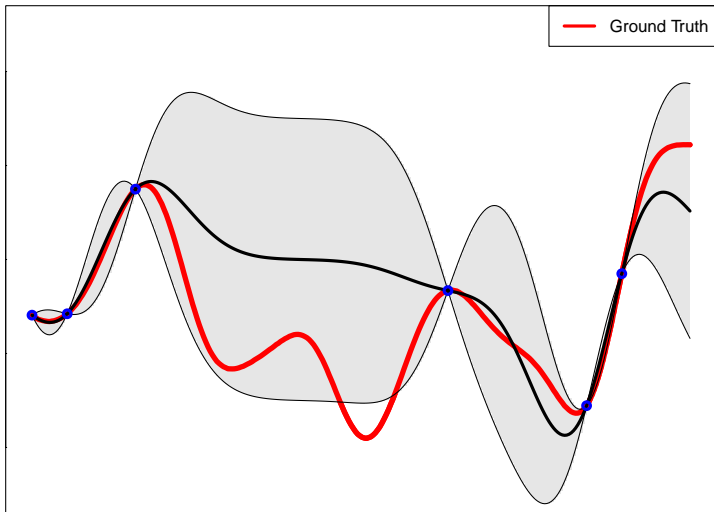
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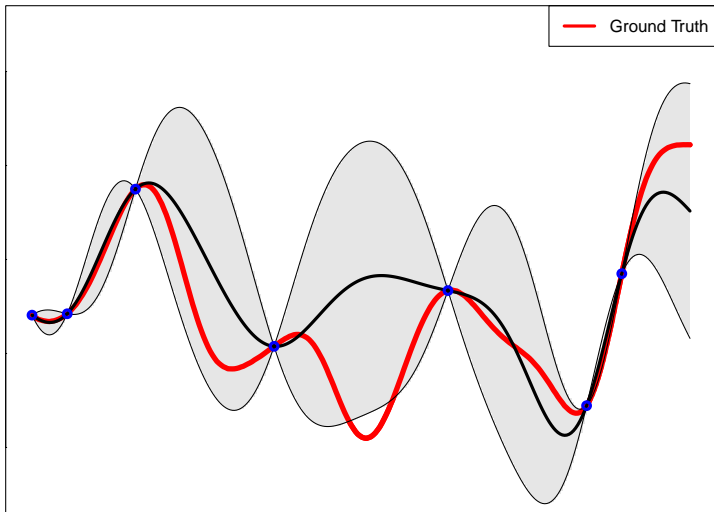
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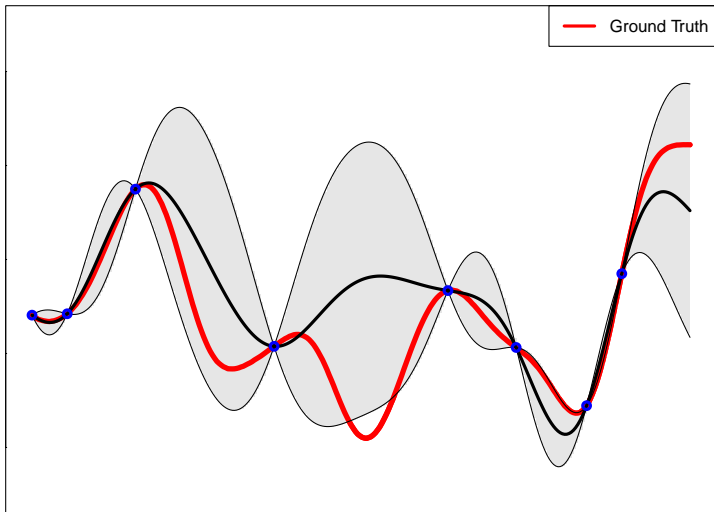
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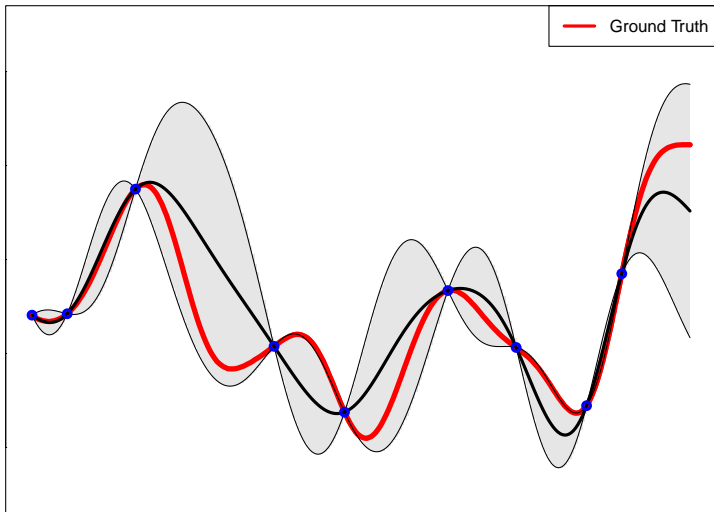
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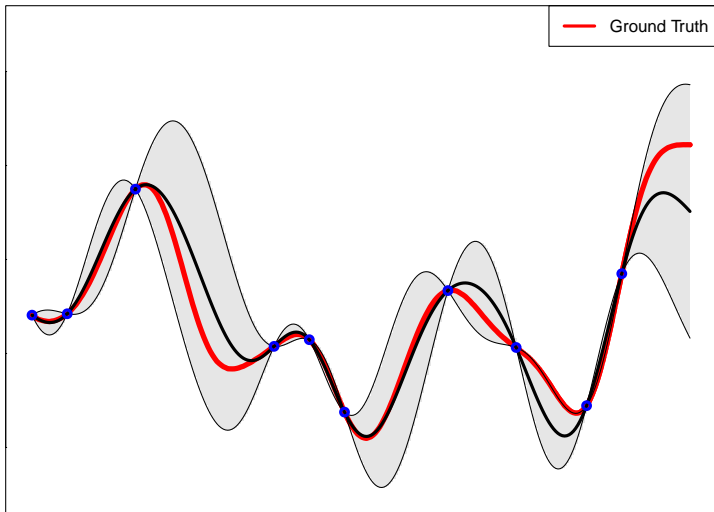
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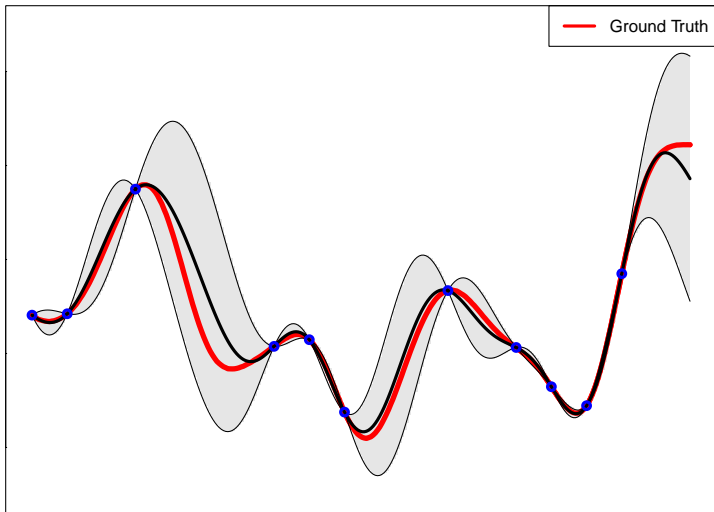
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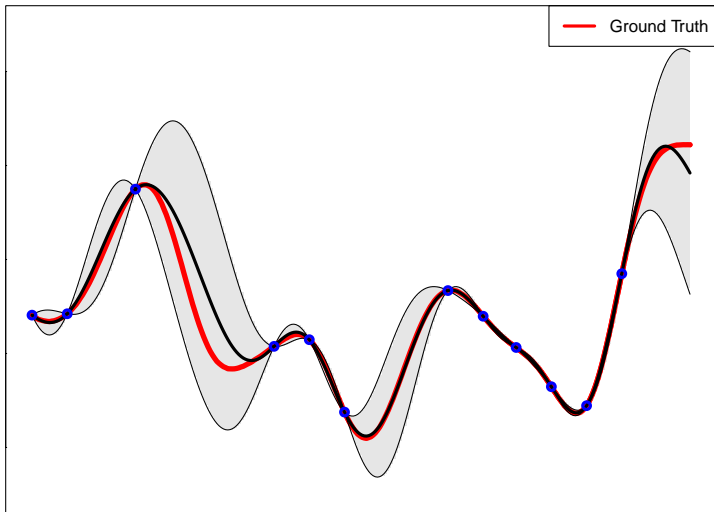
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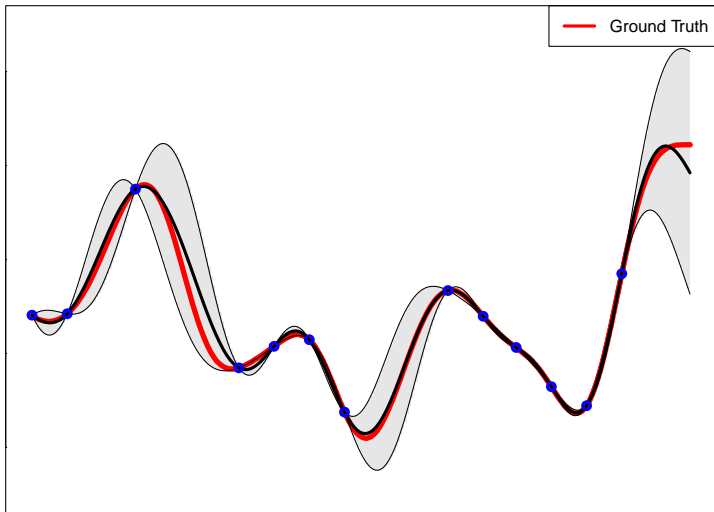
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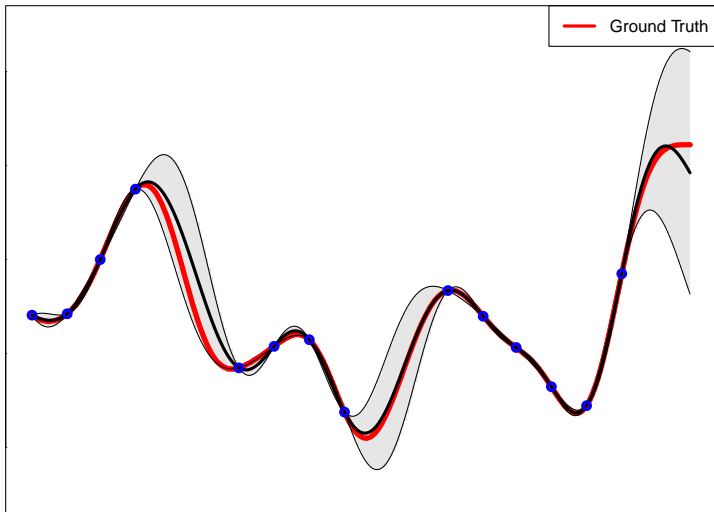
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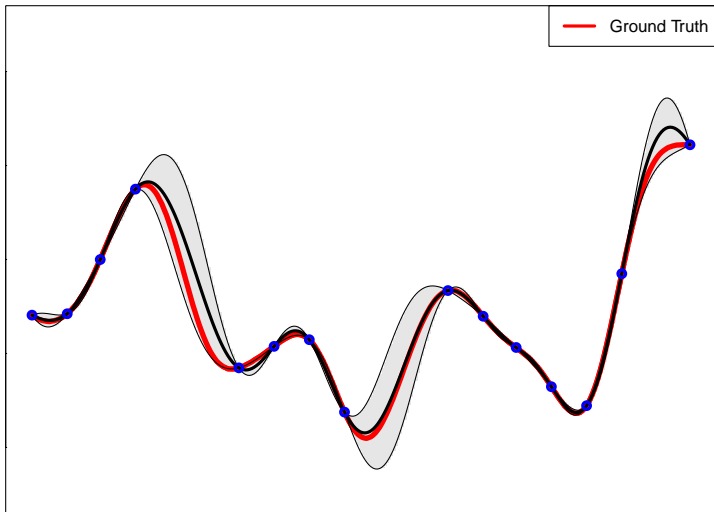
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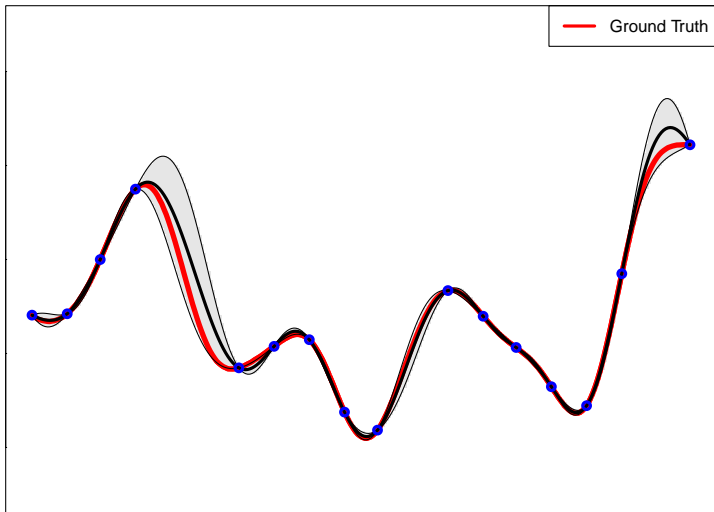
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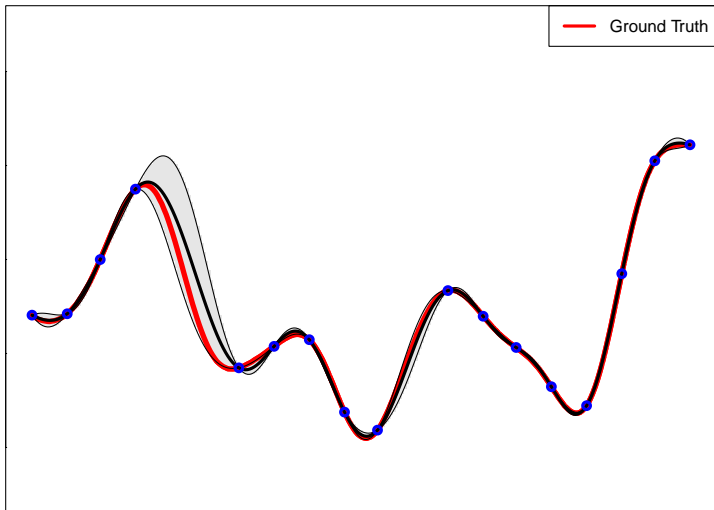
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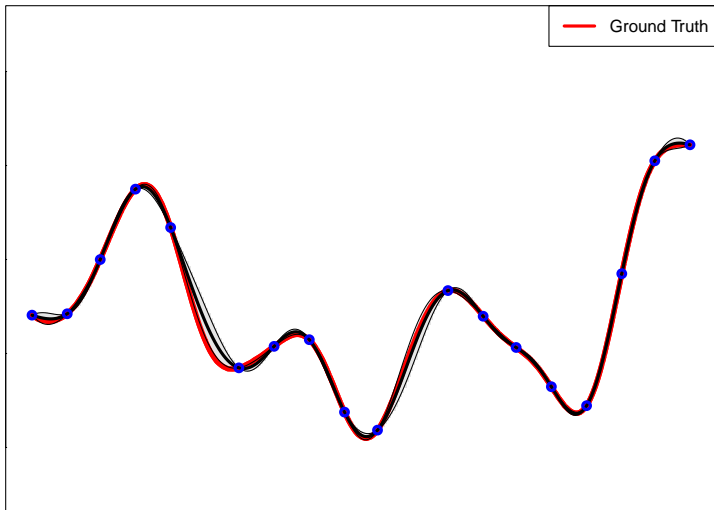
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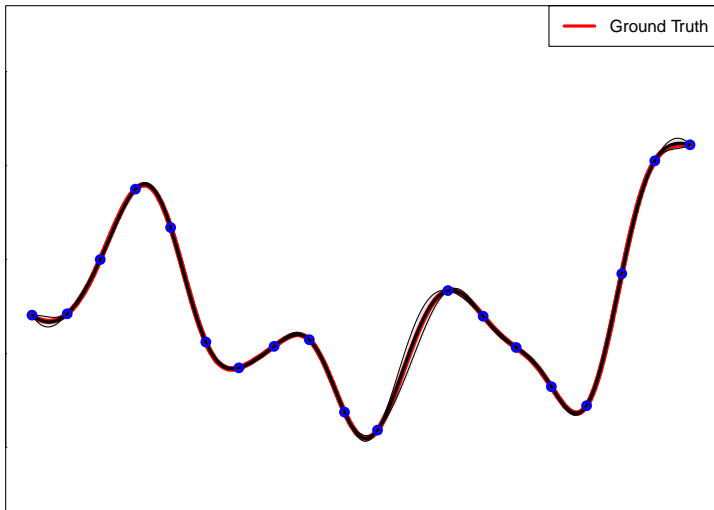
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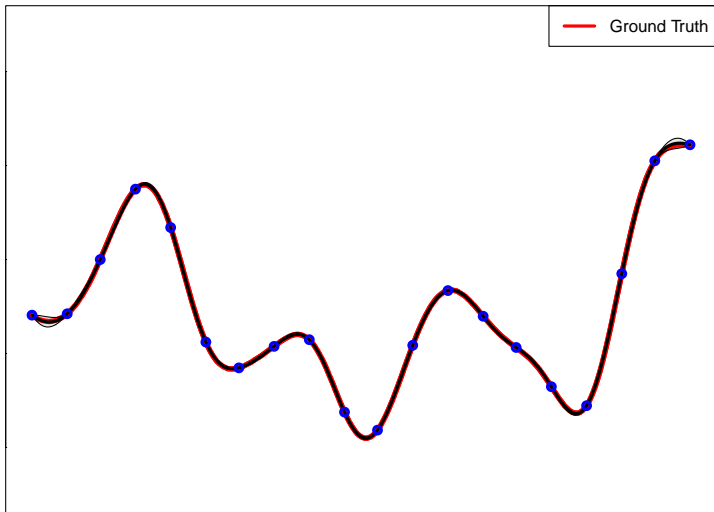
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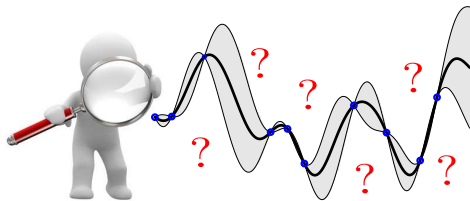


Using the GP Uncertainty in Optimization

Where to evaluate **next**?

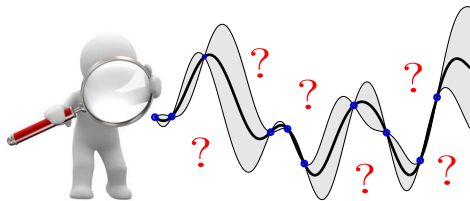
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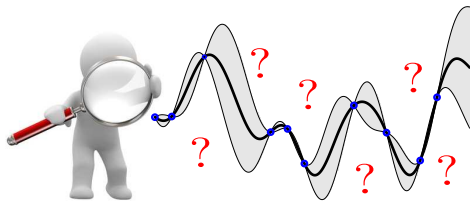
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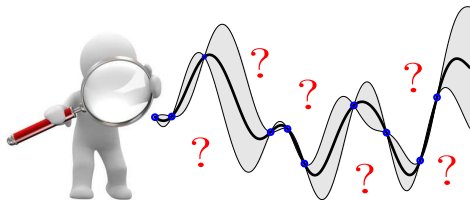
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- **Exploration:** seek places with high variance.
- **Exploitation:** seek places with low mean.

Using the GP Uncertainty in Optimization

Where to evaluate **next**?

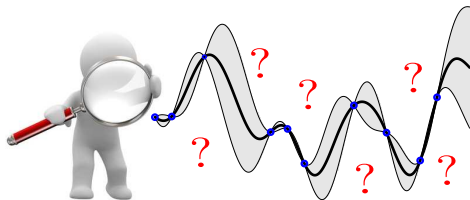


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- **Exploitation:** seek places with low mean.

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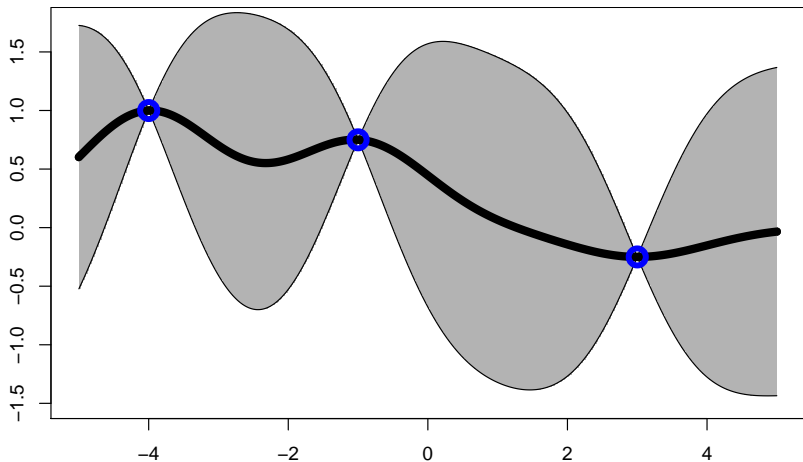
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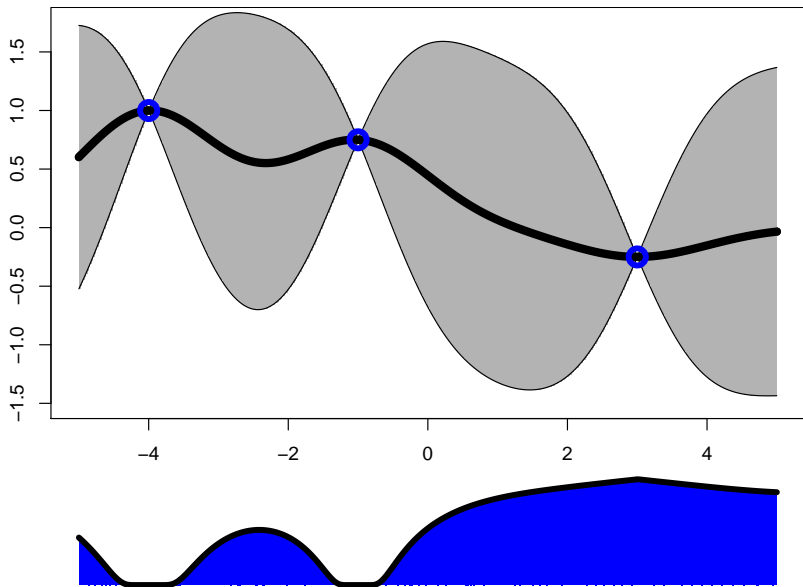
- **Entropy Search:**

$$U(y^* | \mathcal{D}_N, \mathbf{x}) = H[p(\mathbf{x}_{\min} | \mathcal{D}_N)] - H[p(\mathbf{x}_{\min} | \mathcal{D}_N \cup \{\mathbf{x}, y^*\})]$$

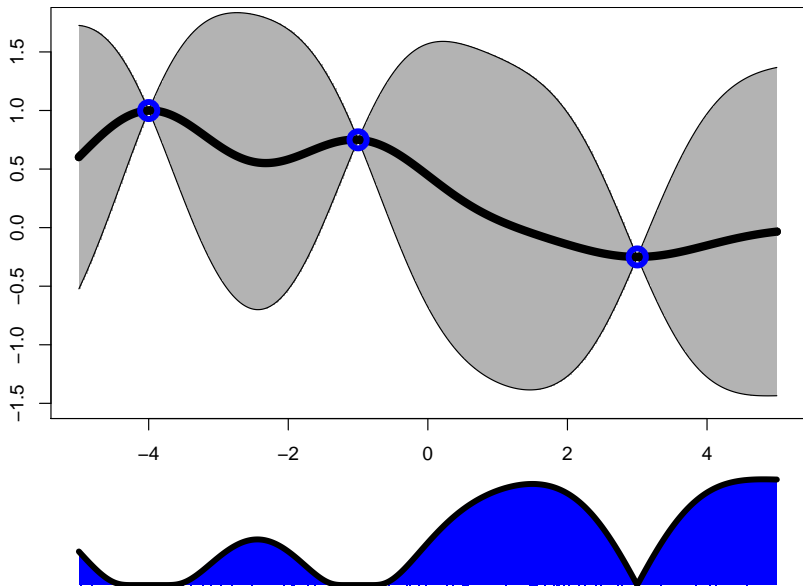
Some Acquisition Functions:



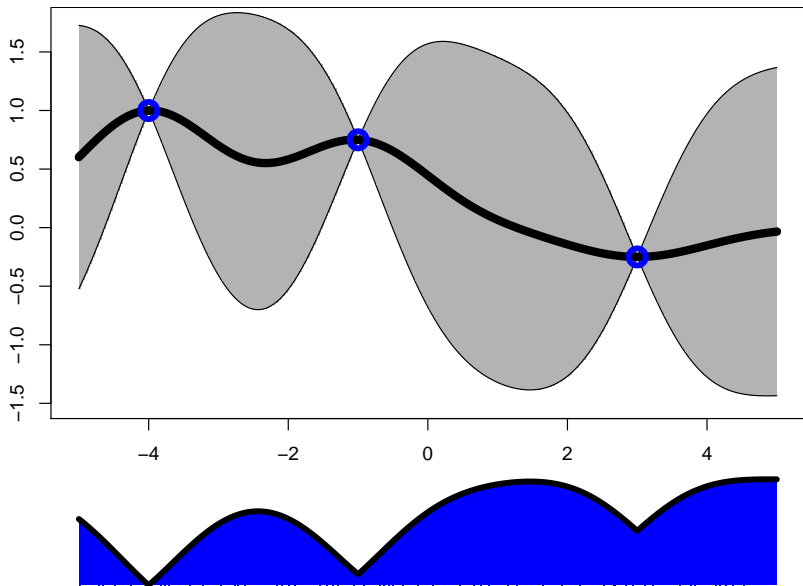
Some Acquisition Functions: Prob. Improvement



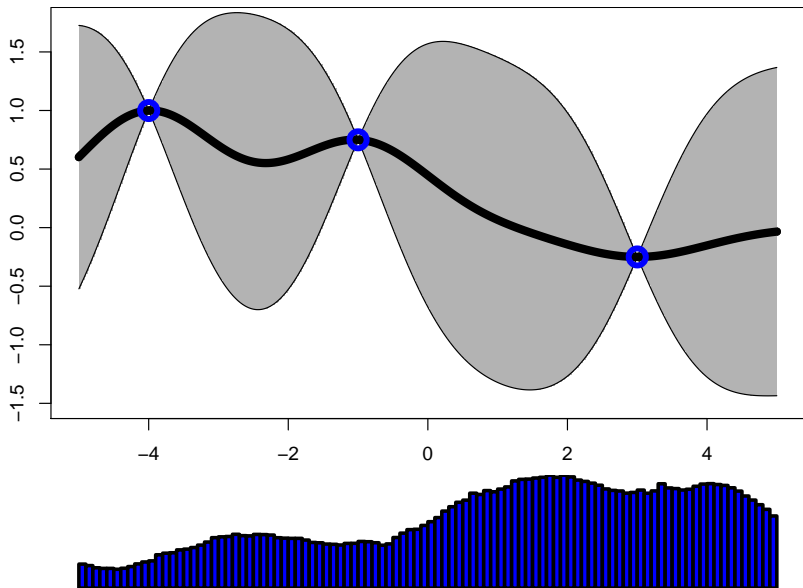
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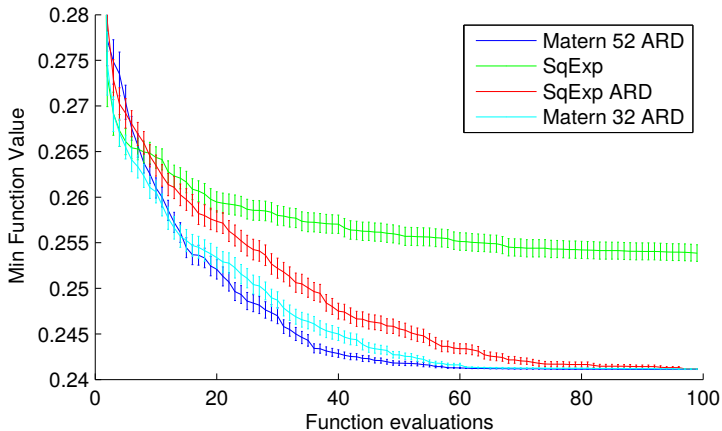


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Structured SVM for protein motif finding (Snoek *et al.*, 2012).

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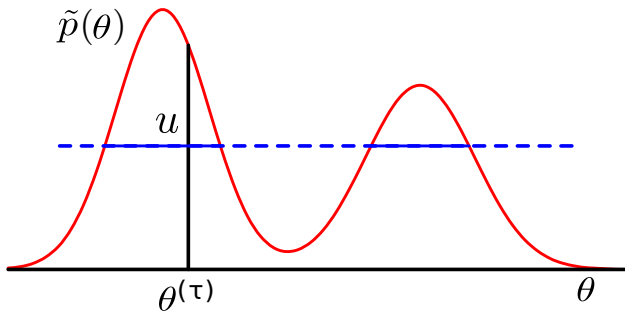
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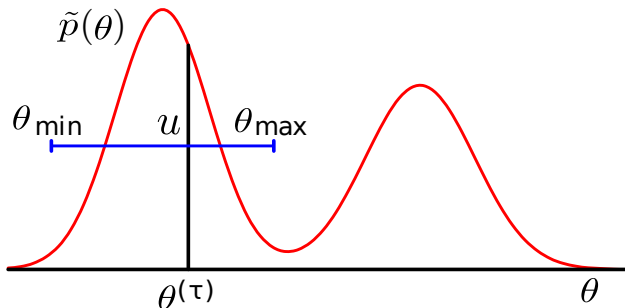
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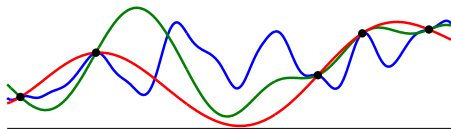
Integrated Acquisition Function

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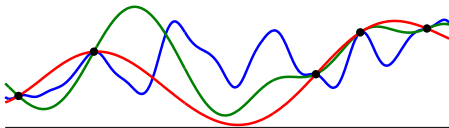
Posterior samples
with three different
length-scales



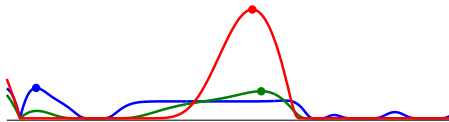
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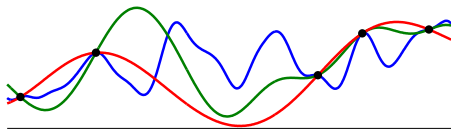
Length-scale specific
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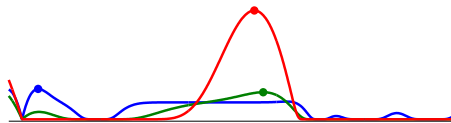
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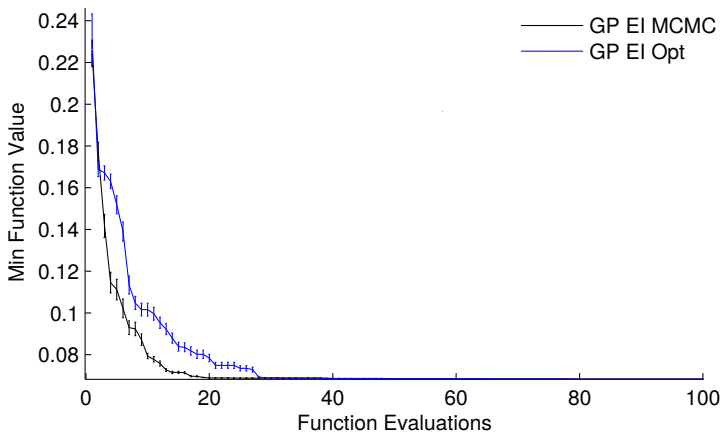
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MCMC estimation vs. Maximization



Logistic regression on the MNIST (Snoek *et al.*, 2012).

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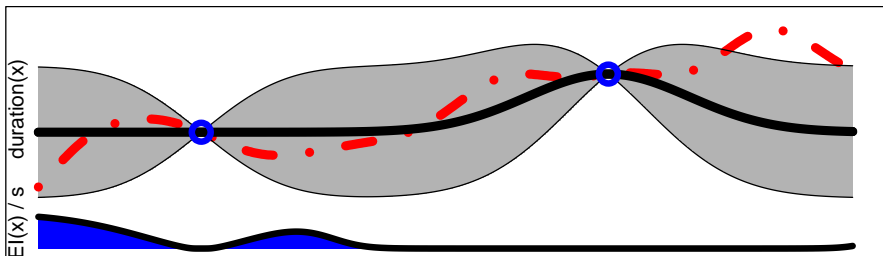
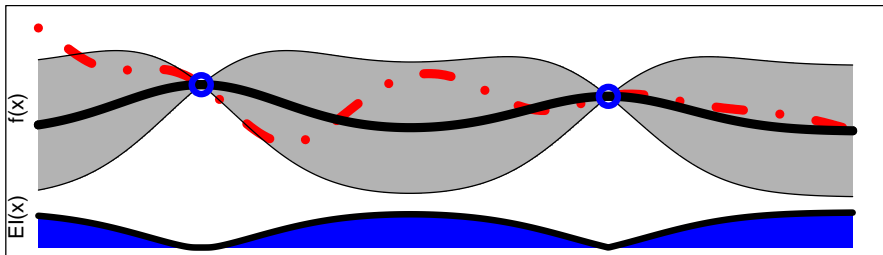
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Expected Improvement per-second:

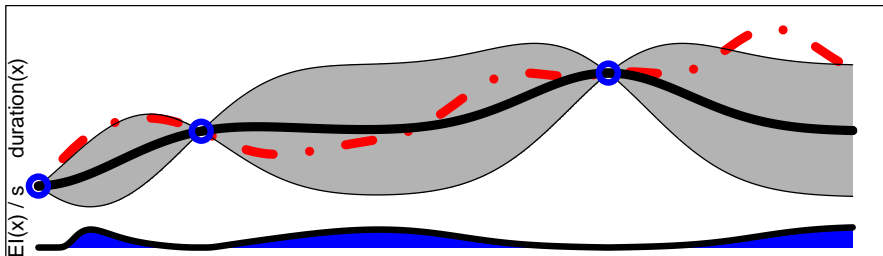
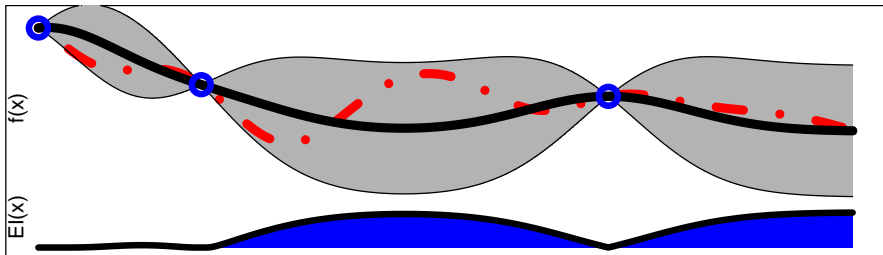
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(Snoek *et al.*, 2012)

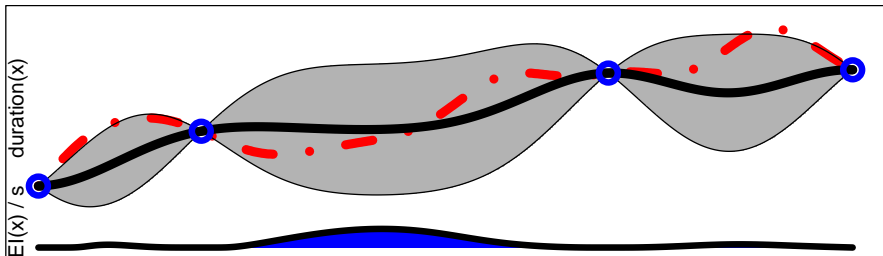
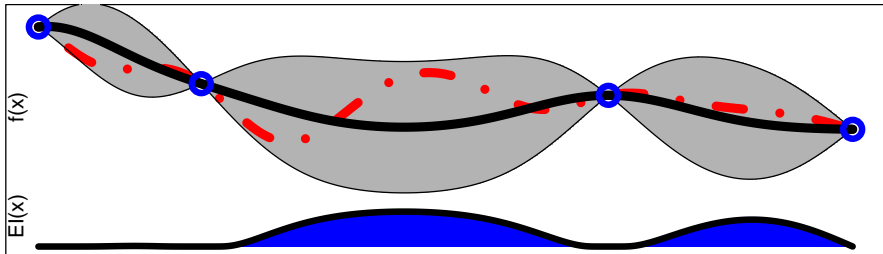
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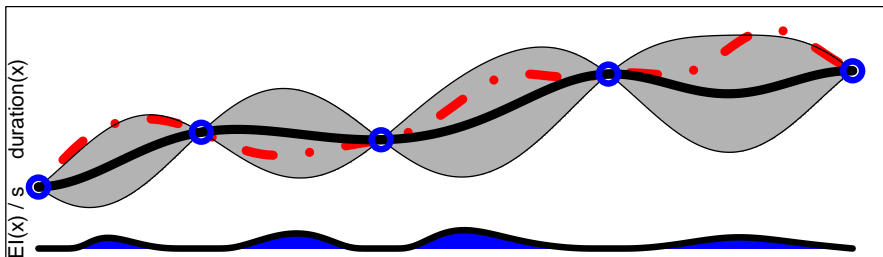
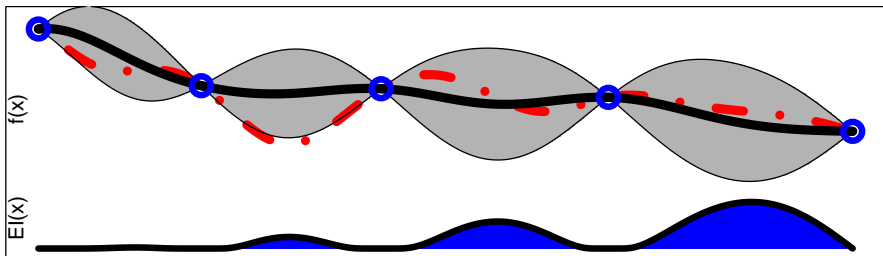
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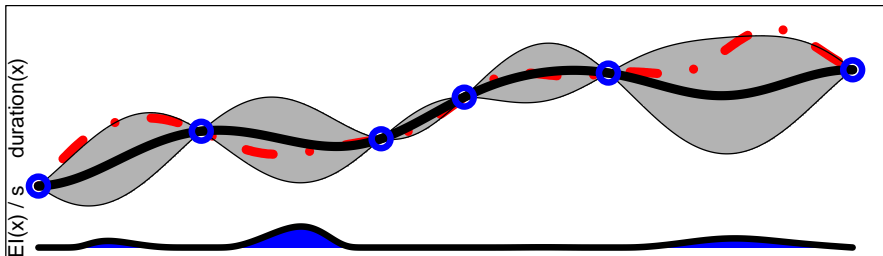
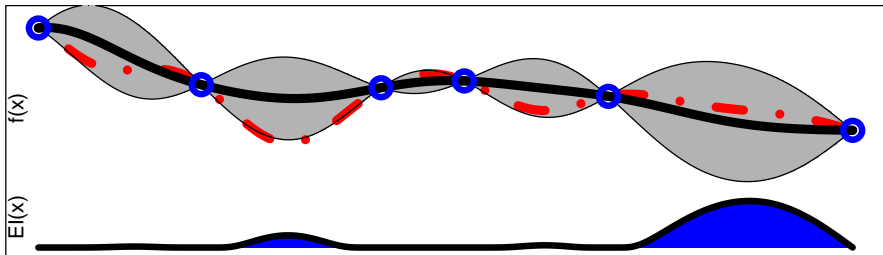
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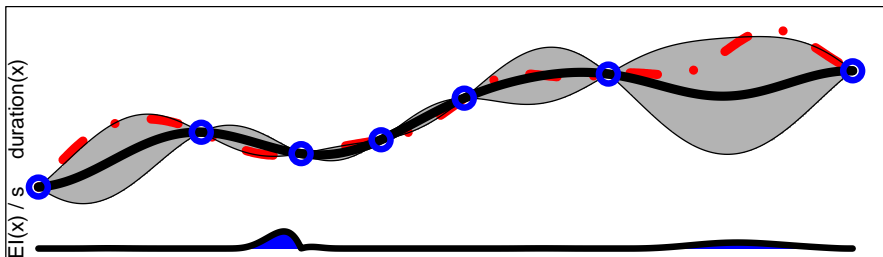
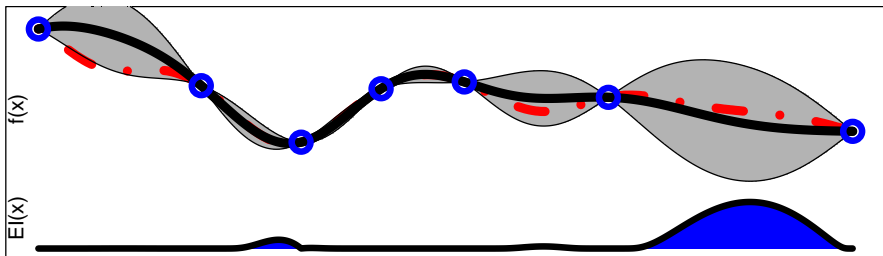
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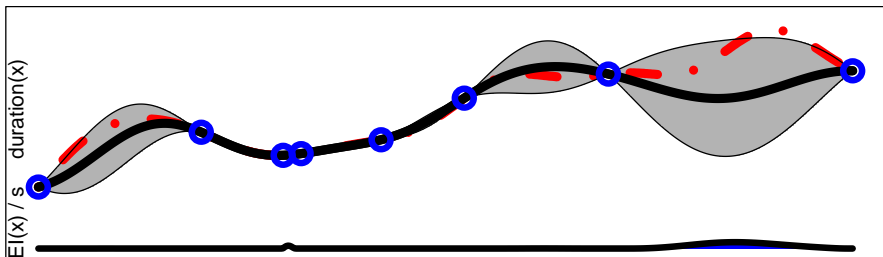
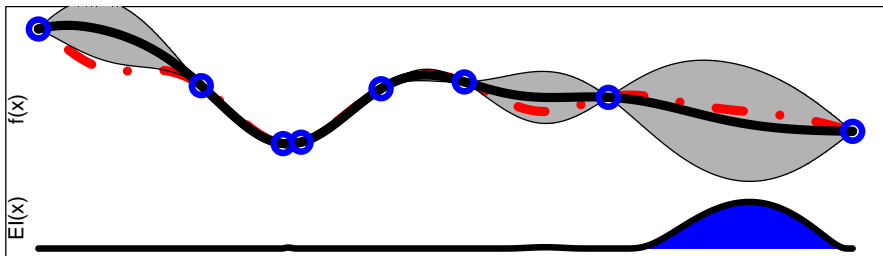
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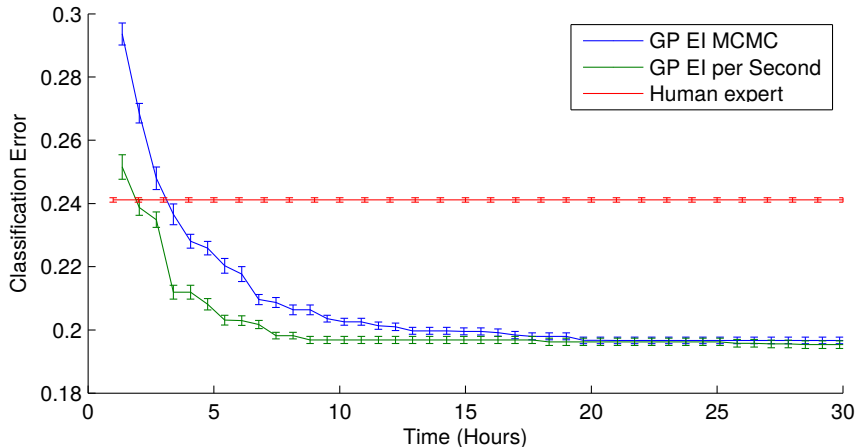
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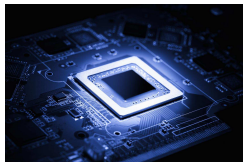
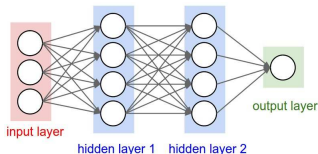
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Deep neural network on the CIFAR dataset (Snoek *et al.*, 2012)

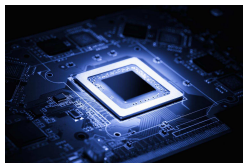
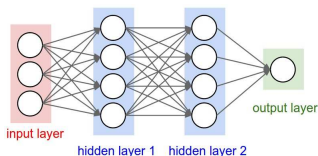
Several Objectives and Constraints

Optimal design of **hardware accelerator** for neural network predictions.



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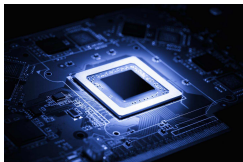
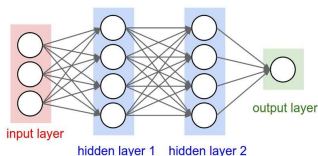


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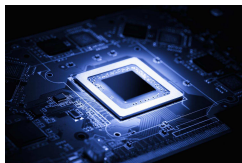
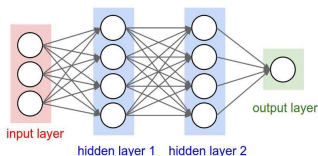
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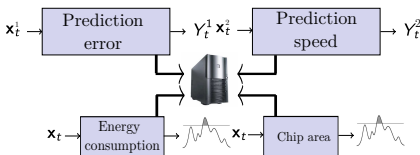


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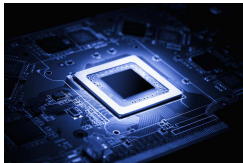
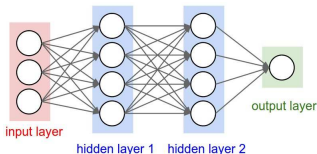
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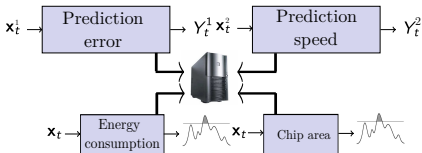


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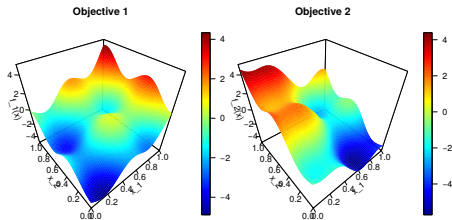
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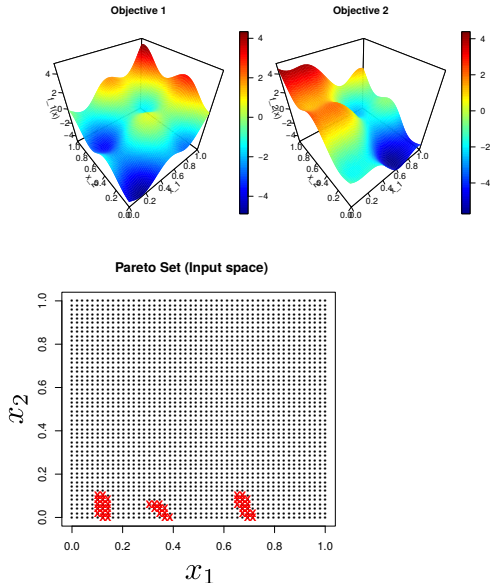
Challenges:

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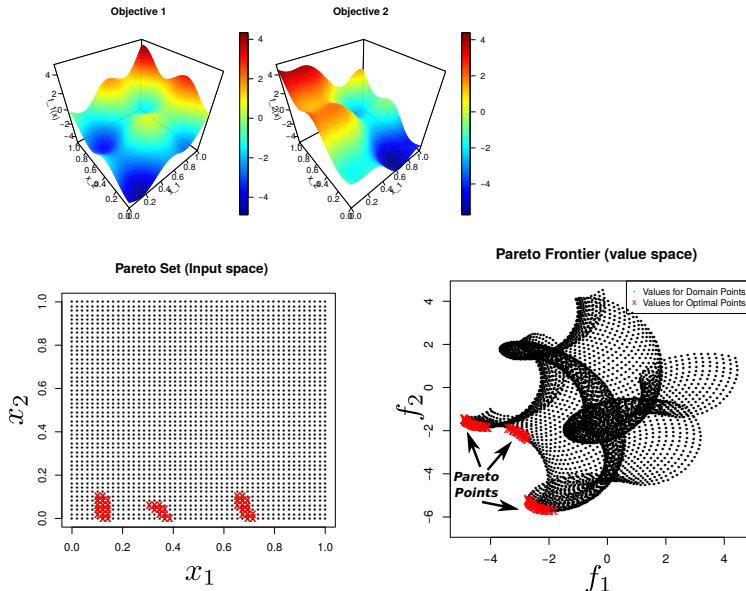
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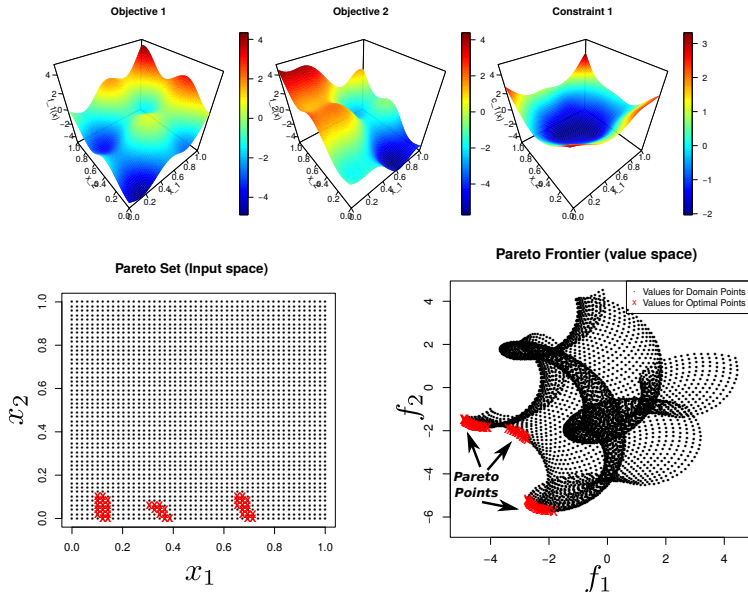
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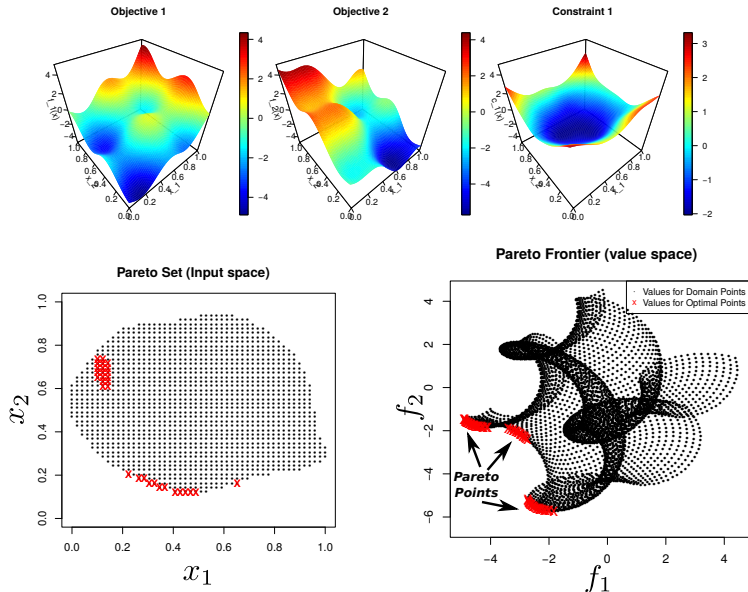
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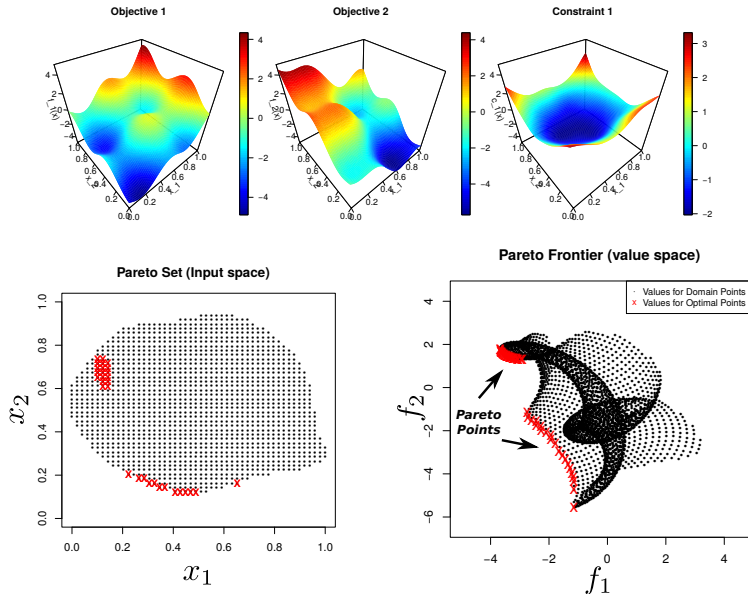
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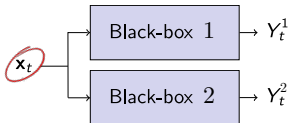
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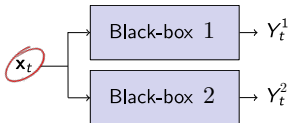


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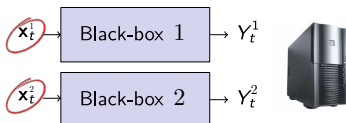
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Decoupled evaluations



Information-based Approach

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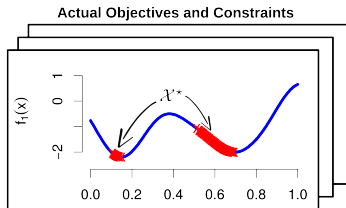
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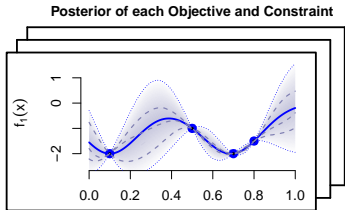
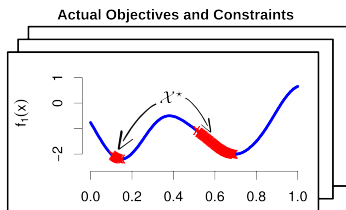
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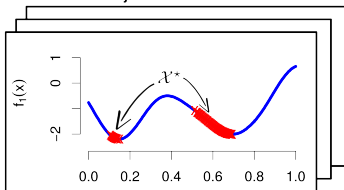


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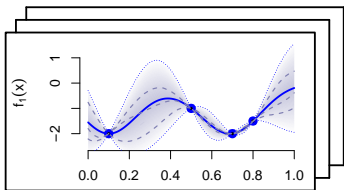
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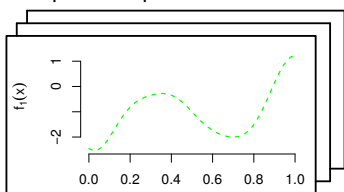
Actual Objectives and Constraints



Posterior of each Objective and Constraint



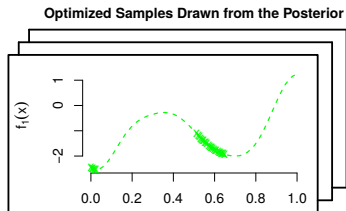
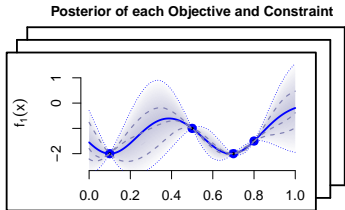
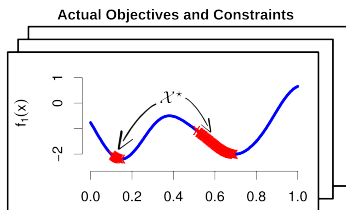
Optimized Samples Drawn from the Posterior



Information-based Approach

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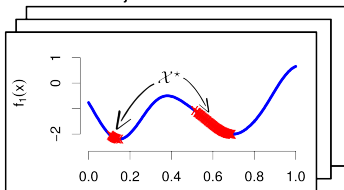


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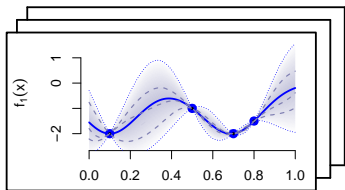
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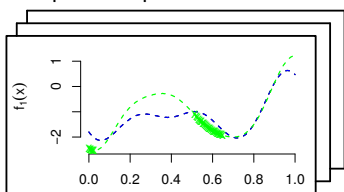
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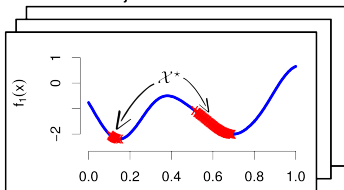


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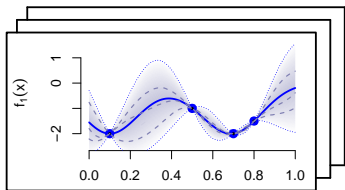
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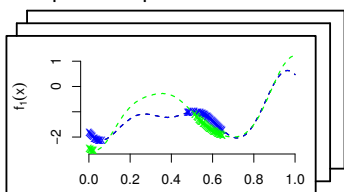
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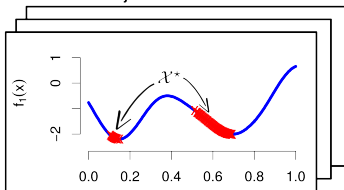


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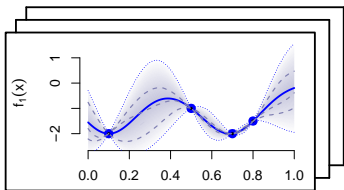
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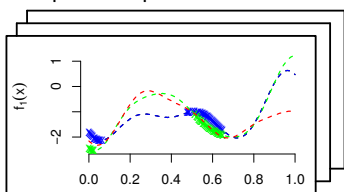
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Posterior of each Objective and Constraint



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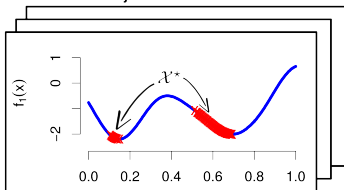


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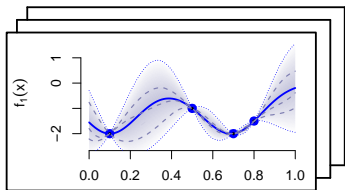
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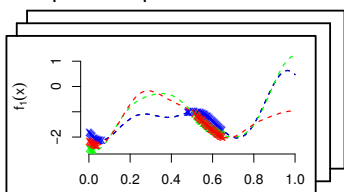
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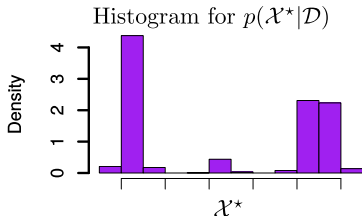
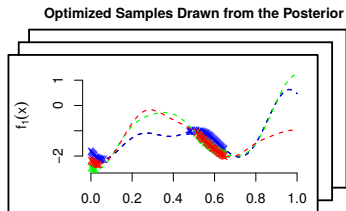
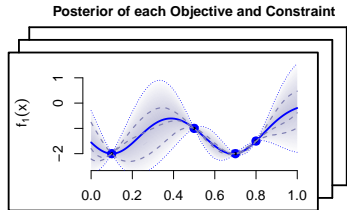
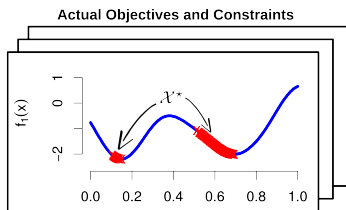
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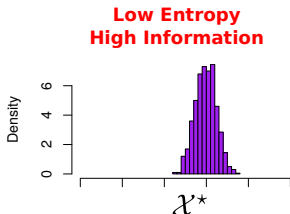
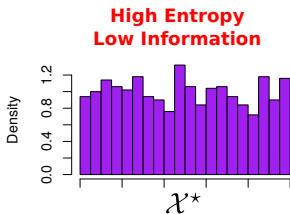
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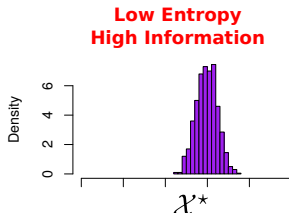
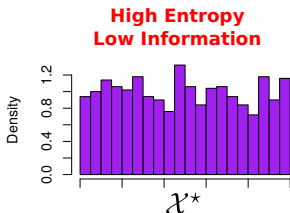
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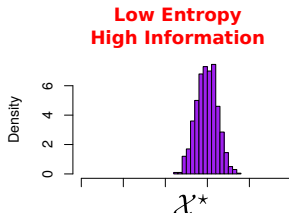
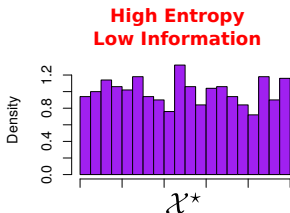
The acquisition function is

$$\alpha(\mathbf{x}) = H[\mathcal{X}^*|\mathcal{D}_t] - \mathbb{E}_{\mathbf{y}} \left[H[\mathcal{X}^*|\mathcal{D}_t \cup \{\mathbf{x}, \mathbf{y}\}] \middle| \mathcal{D}_t, \mathbf{x} \right] \quad (1)$$

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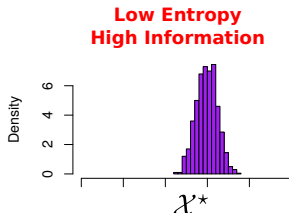
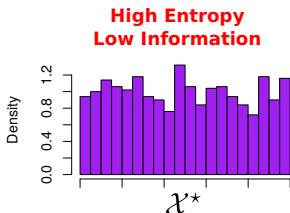
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How much we know
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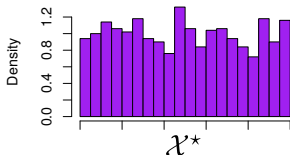
How much we will
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Information-based Approach

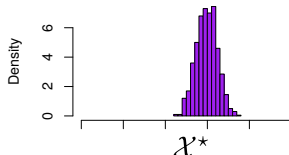
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High Entropy
Low Information



Low Entropy
High Information



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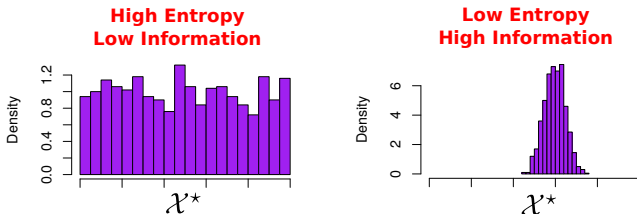
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How much we know about \mathcal{X}^* now.

How much we will know about \mathcal{X}^* after collecting \mathbf{y} at \mathbf{x} .

Computing (1) is **very difficult in practice!**

Predictive Entropy Search (PES)

We **swap y and \mathcal{X}^*** to obtain a reformulation of the acquisition function.

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$$\mathrm{H}[\mathcal{X}^*|\mathcal{D}_t] - \mathbb{E}_{\mathbf{y}}\left[\mathrm{H}[\mathcal{X}^*|\mathcal{D}_t \cup \{\mathbf{x}, \mathbf{y}\}] \middle| \mathcal{D}_t, \mathbf{x}\right] \equiv \textcolor{red}{\mathrm{MI}(\mathbf{y}, \mathcal{X}^*)} \quad (\text{ESMOC})$$

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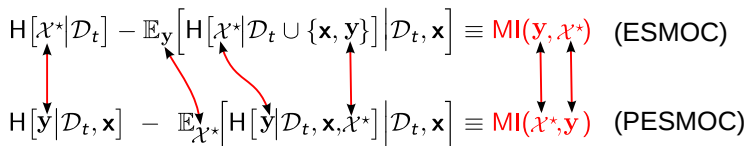
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Gaussian
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Gaussian distribution

Approximated by sampling from $p(\mathcal{X}^* | \mathcal{D}_t)$

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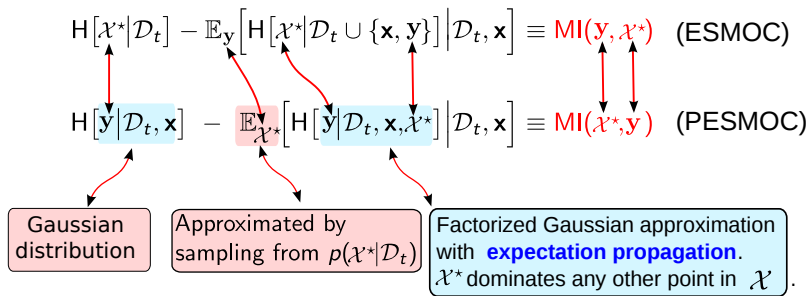
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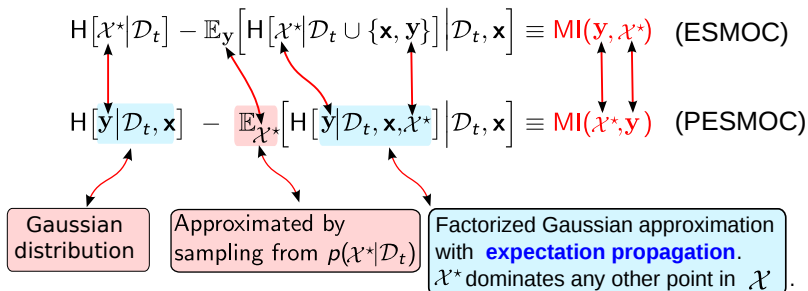
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(Minka, 2001)

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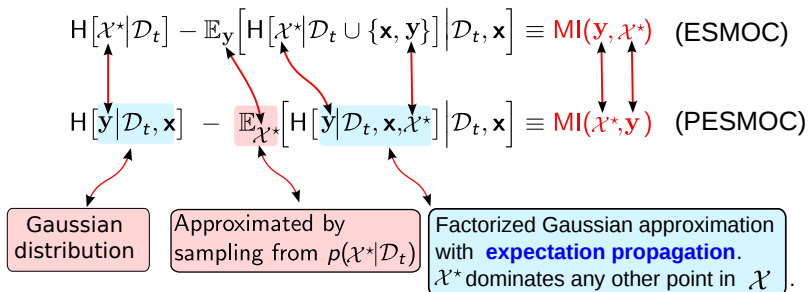


$$\alpha(\mathbf{x}) \approx \sum_{c=1}^C \log v_c^{PD}(\mathbf{x}) - \frac{1}{M} \sum_{m=1}^M \left(\sum_{c=1}^C \log v_c^{CPD}(\mathbf{x} | \mathcal{X}_{(m)}^*) \right) + \sum_{k=1}^K \log v_k^{PD}(\mathbf{x}) - \frac{1}{M} \sum_{m=1}^M \left(\sum_{k=1}^K \log v_k^{CPD}(\mathbf{x} | \mathcal{X}_{(m)}^*) \right)$$

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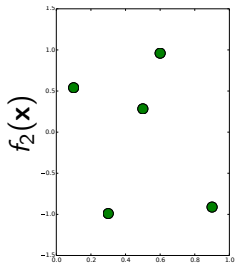
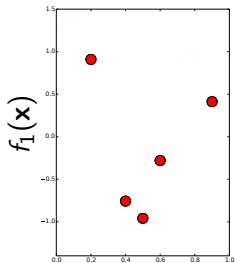
Approximated by sampling from $p(\mathcal{X}^* | \mathcal{D}_t)$

Factorized Gaussian approximation with **expectation** \mathcal{X}^* dominates any One acquisition per black-box.

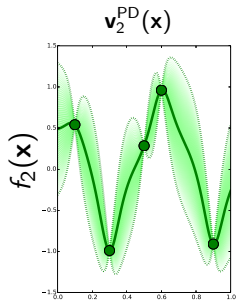
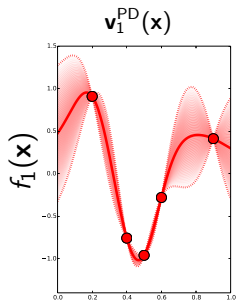
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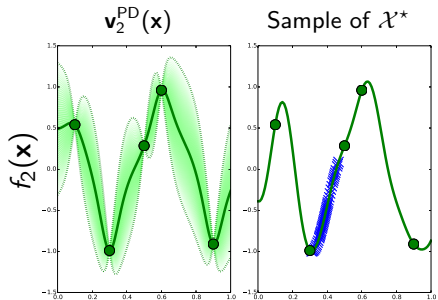
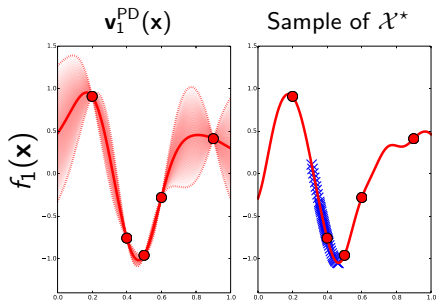
Example of PES' acquisition



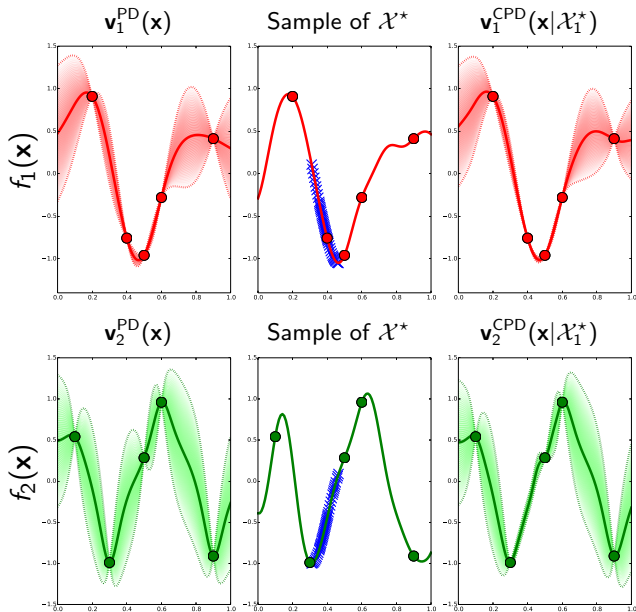
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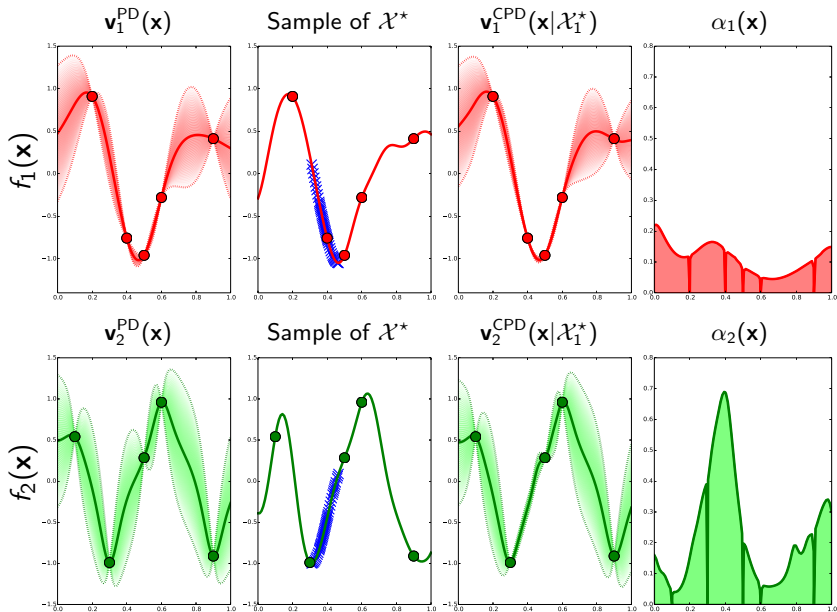
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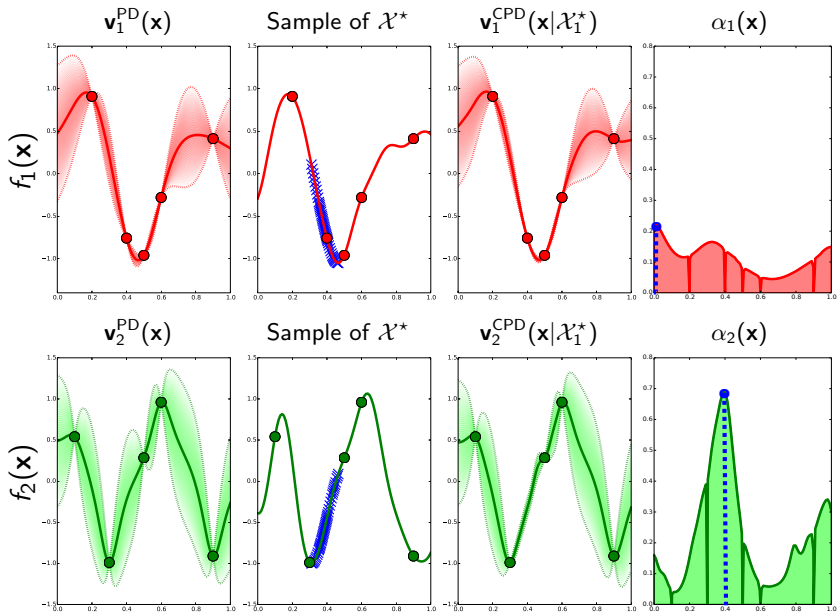
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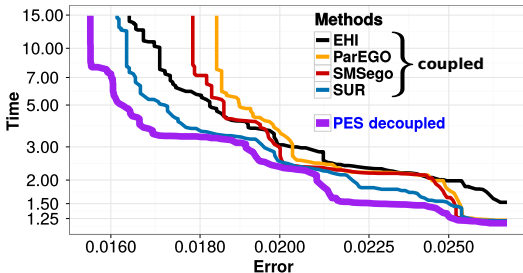


Example of PES' acquisition



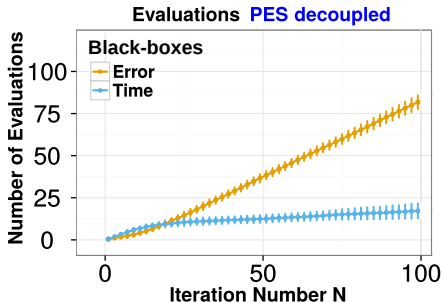
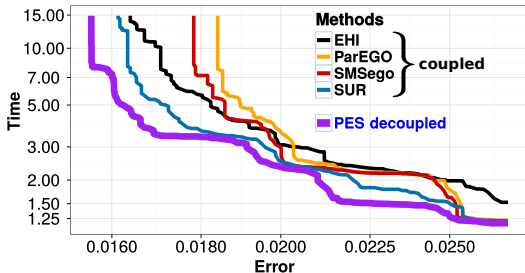
Finding a Fast and Accurate Neural Network

Average Pareto Front 100 Function Evaluations



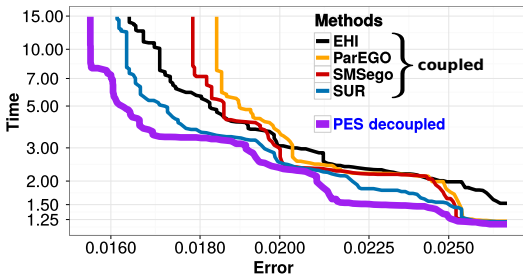
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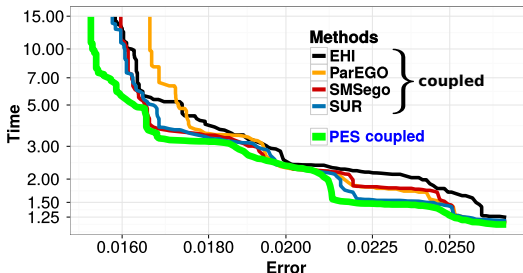


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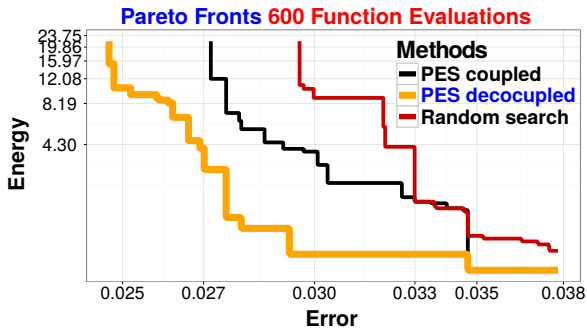
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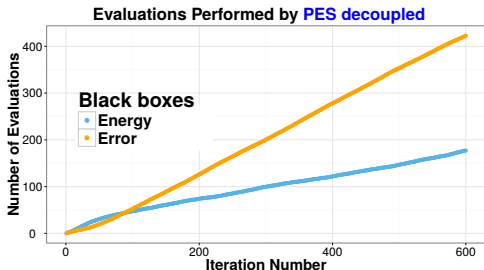
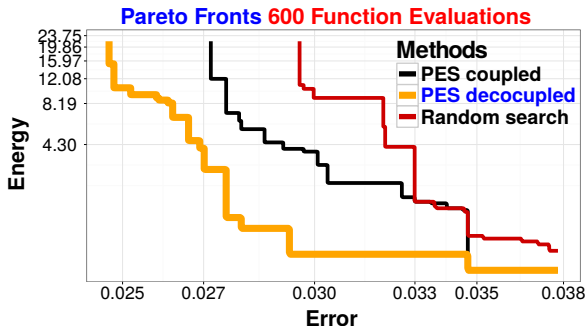
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Low energy hardware accelerator



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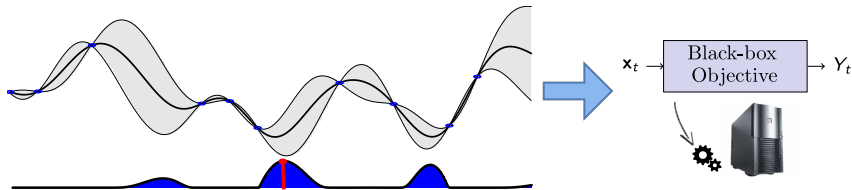


Parallel Bayesian Optimization

Traditional Bayesian optimization is **sequential**!

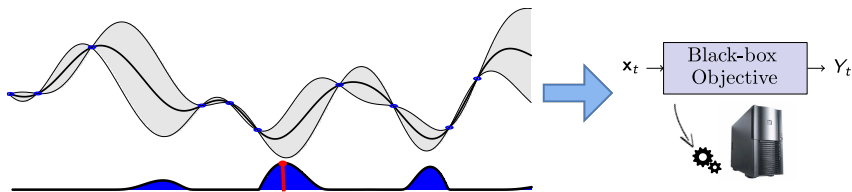
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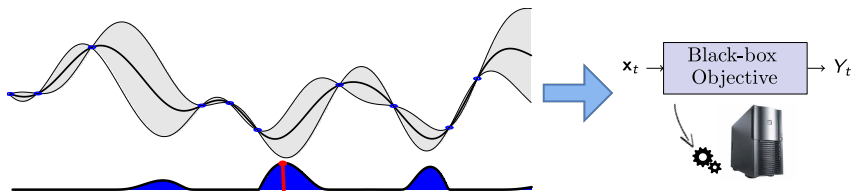
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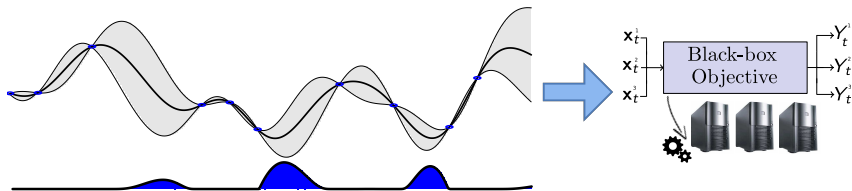
Computing clusters let us do **many things** at once!

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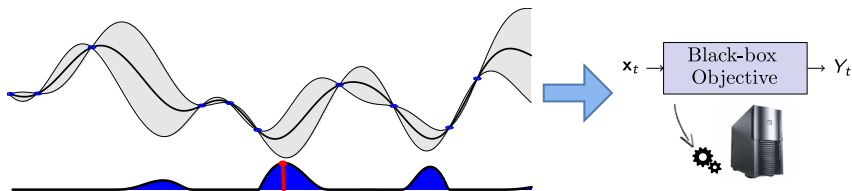


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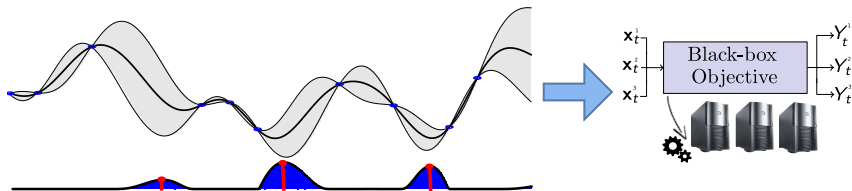


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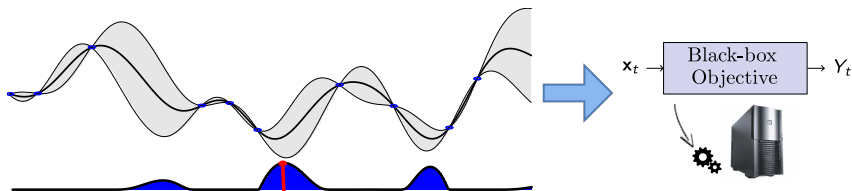


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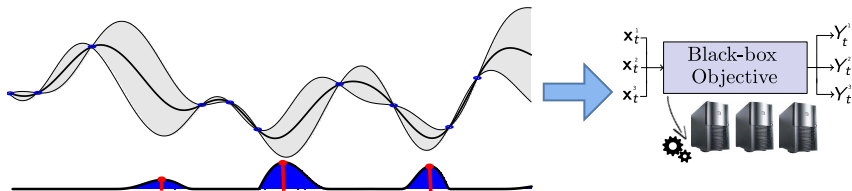


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Parallel experiments should be highly informative but different!

Parallel Predictive Entropy Search

Choose a set Q points $\mathcal{S}_t = \{\mathbf{x}_q\}_{q=1}^Q$ to minimize the entropy of \mathbf{x}^* .

$$H[\mathbf{x}^* | \mathcal{D}_t] - \mathbb{E}_{\mathbf{y}} \left[H[\mathbf{x}^* | \mathcal{D}_t \cup \{\mathbf{x}_q, y_q\}_{q=1}^Q} \middle| \mathcal{D}_t, \mathbf{x} \right] \equiv \text{MI}(\mathbf{y}, \mathbf{x}^*) \quad (\text{Parallel ES})$$

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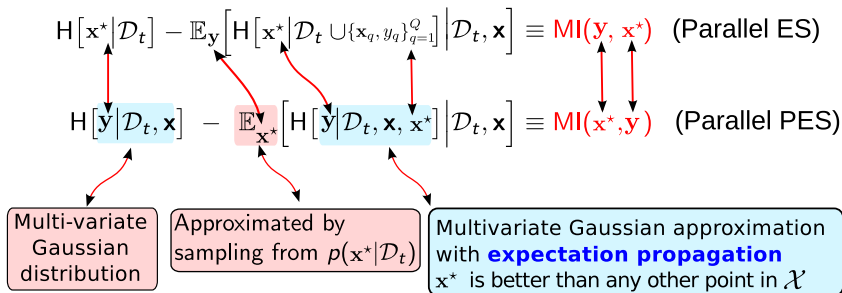
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Multivariate Gaussian approximation with **expectation propagation**
 \mathbf{x}^* is better than any other point in \mathcal{X}

$$\alpha(\mathcal{S}_t) = \log |\mathbf{V}^{\text{PD}}(\mathcal{S}_t)| - \frac{1}{M} \sum_{m=1}^M \log |\mathbf{V}^{\text{CPD}}(\mathcal{S}_t | \mathbf{x}_{(m)}^*)|$$

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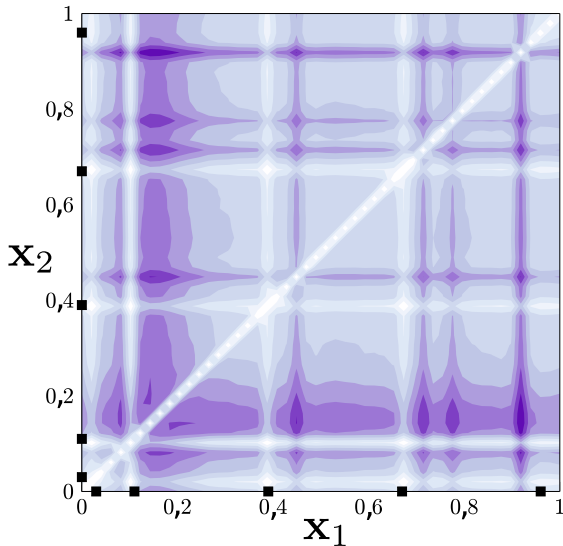
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It is possible to compute the gradient of $\alpha(\cdot)$ w.r.t. each $\mathbf{x}_q \in \mathcal{S}_t$!

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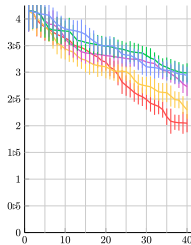
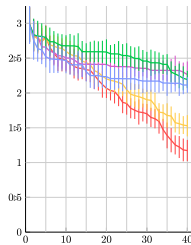
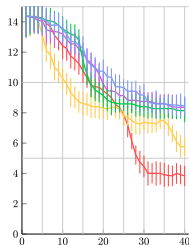
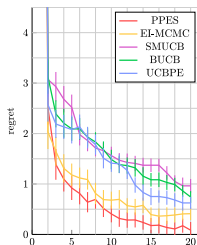
Parallel Predictive Entropy Search: Level Curves



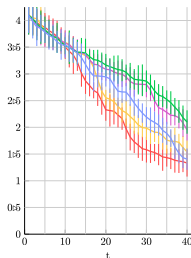
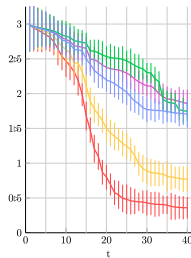
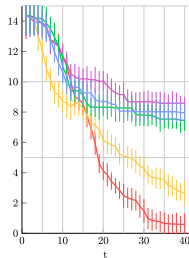
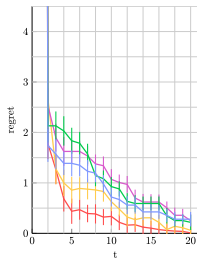
(Shah and Ghahramani, 2015)

Parallel Predictive Entropy Search: Results

batch_size=2



batch_size=4



(a) boston

(b) hydrogen

(c) rocket

(d) robot

(Shah and Ghahramani, 2015)

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Other tools: SMAC (Java), Hyperopt (Python), Bayesopt (C++), PyBO (Python), MOE (Python / C++).

Further Extensions and Open Issues

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- ④ **Safe Bayesian Optimization:** Sometimes we should avoid evaluating the objective at particular input locations (system failure) where it falls below some critical value (Berkenkamp *et al.*, 2016).

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Thank you very much!

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